

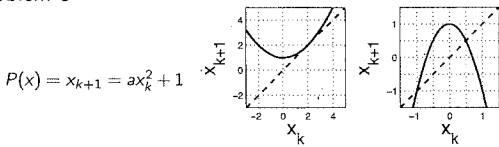
Name SOLUTIONS

Midterm Exam
May 2, 2013

- _____ Problem 0 (5 points) : Turn in one-page cheat sheet.
- _____ Problem 1 (10 points)
- _____ Problem 2 (10 points)
- _____ Problem 3 (15 points)
- _____ Problem 4 (20 points)
- _____ Problem 5 (15 points)
- _____ Problem 6 (25 points)

- _____ Total (out of 100)

Problem 3



Above is a return map, $P(x)$, for a 1D discrete-time system (at left), with instances of $P(x)$ for two different values of a (right).

- Write an expression to solve for the fixed points. (Do not bother to simplify this expression!)
- Write an expression for the slope of $P(x)$.
- For what values of a does the system have 1 stable and 1 unstable fixed point?

a) $x^* = a(x^*)^2 + 1$

b) $\frac{dP}{dx} = 2ax$

c) For slope = -1, $-1 = 2ax \Rightarrow x = \frac{-1}{2a}$

$0 = a\left(\frac{-1}{2a}\right)^2 - \left(\frac{-1}{2a}\right) + 1$

$-1 = \frac{1}{4a} + \frac{2}{4a}$

$a = \frac{-3}{4}$

For slope = +1,

$-1 = \frac{1}{4a} - \frac{2}{4a}$

$a = +\frac{1}{4}$

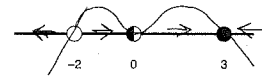
But: For slope = 0

← only one (stable) fixed point! So...

$a \neq 0$ and $-\frac{3}{4} < a < +\frac{1}{4}$

to keep slope magnitude less than one

Problem 1



- Write a valid expression for $f(x)$ that agrees with the figure.
- Sketch $f(x)$ and draw arrows along the x -axis to indicate the direction of flow on the line.

a) $f(x) = -(x+2)x^2(x-3)$

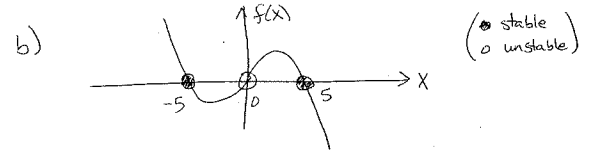
b)

Problem 2

$f(x) = 25x - x^3$

- Find all fixed points for $f(x)$.
- Sketch $f(x)$, indicating fixed point locations and their stability.

a) $0 = x^*(25 - (x^*)^2) \Rightarrow x^* = 0, -5, 5$



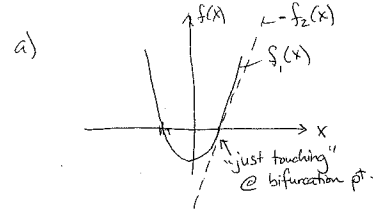
Problem 4

$f(x) = f_1(x) - f_2(x) = x^4 - 1 + r(x-1)$

Define: $f_1(x) = x^4 - 1$

and: $f_2(x) = -r(x-1)$

- Sketch $f_1(x)$, as a first step.
- Now, find r_c and x_c^* at the point of bifurcation.
- Identify the type of bifurcation.
- Sketch the bifurcation diagram (x^* vs r). Do not try to capture the exact shape, but do clearly illustrate the directions and stability of all branches. (Take care that your bifurcation actually occurs at the r_c and x_c^* location you previously found!)



b) Both intersect (f_1, f_2) always @ $x_c^* = 1$

Slope = 0 = $(4x^3 + r)$ at $x_c^* = 1, r_c = 4 + r_c \Rightarrow r_c = -4$

c) Transcritical, Non-symm., w/ $x^* = 1$ never "disappearing"



"bowl" shape, i.e. "attracting"...

Larger value unstable x^*

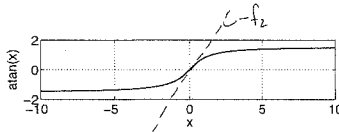
$(1+X)^4 - 1 + (-4+R)X = 0$

$(1+4X+6X^2+4X^3+X^4) - 1 - 4X + RX = 0$

$6X^2 + RX = 0 \Rightarrow X^* = 0, \frac{R}{6}$

(keep X^2 & lower terms)

Problem 5



Above is a sketch of the arctangent function.
(Recall that $\tan(\delta) \approx \delta$, for small delta.)

$$f(x) = rx + \text{atan}(x)$$

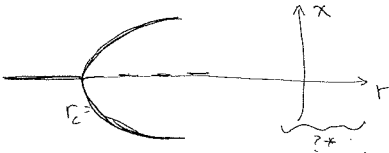
- Solve for r_c and x_c^* at the bifurcation point.
- Identify the type of bifurcation.
- Sketch the bifurcation diagram. As in Problem 3: Do not try to capture the exact shape, but do clearly illustrate the directions and stability of all branches. (Take care that your bifurcation actually occurs at the r_c and x_c^* location you previously found!)

a) Always $f_1, \dot{x}, -f_2$ intersect @ $x_c^* = 0$
Matching slope $r_c = -1$, since slope of $\text{atan}(x)|_{x=0} = +1$

b) **Supercritical Pitchfork**

because 2 stable & 1 unstable x^* values.

c) 3 branches for lower magn. (but negative)
 r values: 3 branches for $r_c < r < 0$



[* Note: Just describes behavior locally, near r_c . ($r > 0$ has only 1 solution)]

Problem 6

$$A = \begin{bmatrix} -3 & 5 \\ 1 & 1 \end{bmatrix}$$

- Find eigenvalues and eigenvectors of A .
- Write the linear dynamic equations for the 2 states, x and y .
- On the axes below, sketch the eigenvectors as solid lines.
- Then, sketch nullclines (i.e., $\dot{x} = 0$ and $\dot{y} = 0$) as dashed lines.
- And sketch flow pattern (sample trajectories) in 2D phase space.

a) $\tau = -3+1 = -2$, $\Delta = (-3)(1) - (5)(1) = -8$

b) $\lambda_1 = \frac{1}{2}(-2 + \sqrt{(-2)^2 - 4(-8)}) = \frac{1}{2}(-2 + 6) = \frac{4}{2}$

$$\begin{bmatrix} \lambda_1 = +2 \\ \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{bmatrix} \quad [(-3-2), 5] \begin{bmatrix} v_{1x} \\ v_{1y} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\lambda_2 = \frac{1}{2}(-2 - 6)$$

$$\begin{bmatrix} \lambda_2 = -4 \\ \vec{v}_2 = \begin{bmatrix} 5 \\ -1 \end{bmatrix} \end{bmatrix} \quad [(-3+4), 5] \vec{v}_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$b) \Rightarrow \begin{cases} \dot{x} = -3x + 5y \\ \dot{y} = x + y \end{cases}$$

d) $\dot{x} = 0 = -3x + 5y$
 $y = \frac{3}{5}x$ ← $\dot{x} = 0$ nullcline
 $0 = x + y$
 $y = -x$ ← $\dot{y} = 0$ nullcline

