

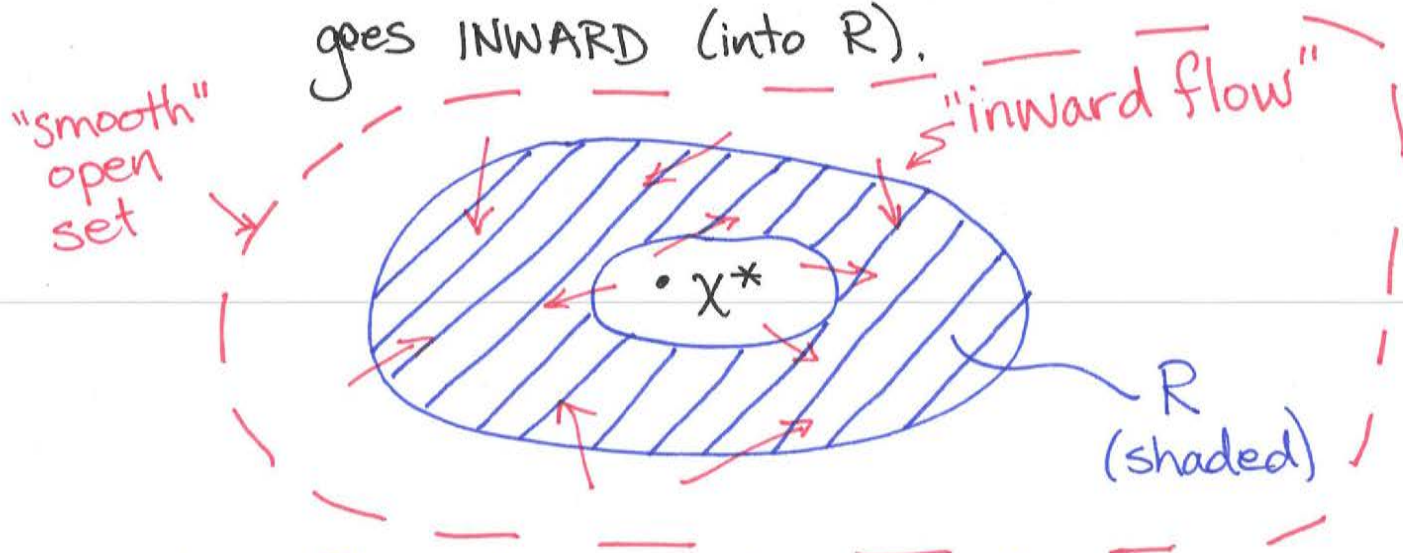
Methods to show a closed orbit DOES exist:

1. Poincaré-Bendixson Theorem.
2. Lienard's Theorem.

1. Poincaré-Bendixson Thm. (P-B Thm)

For a 2D system,  $\dot{\vec{x}} = \vec{f}(\vec{x})$ ,  $\vec{x} \in \mathbb{R}^2$ ,  
where  $\vec{f}(\vec{x})$  is "smooth enough" over some  
open set, we look for the following  
conditions on some closed, bounded  
region  $R$ :

- a)  $R$  is within the "smooth enough" set.
- b)  $R$  contains NO FIXED POINTS.
- c) Flow on all boundaries of  $R$   
goes INWARD (into  $R$ ).



→ Then  $R$  contains a closed orbit.

• Examples 7.3.2 / 7.3.3 (Strogatz)

Glycolysis. Biochemical process to break down sugar (for energy).

$$\dot{x} = -x + ay + x^2y$$

$$\dot{y} = b - ay - x^2y$$

( $a, b \rightarrow$  kinetic parameters)

$x$ : concentration of ADP

$y$ : concentration glucose

- Let's try to demonstrate oscillations exist...

a) Nullclines:

$$\dot{x} = 0 = -x + ay + x^2y \rightarrow$$

$$y_1 = \frac{x}{a + x^2}$$

$$\dot{y} = 0 = b - ay - x^2y \rightarrow$$

$$y_2 = \frac{b}{a + x^2}$$

b) Fixed Point(s):

Set  $y_1 = y_2$

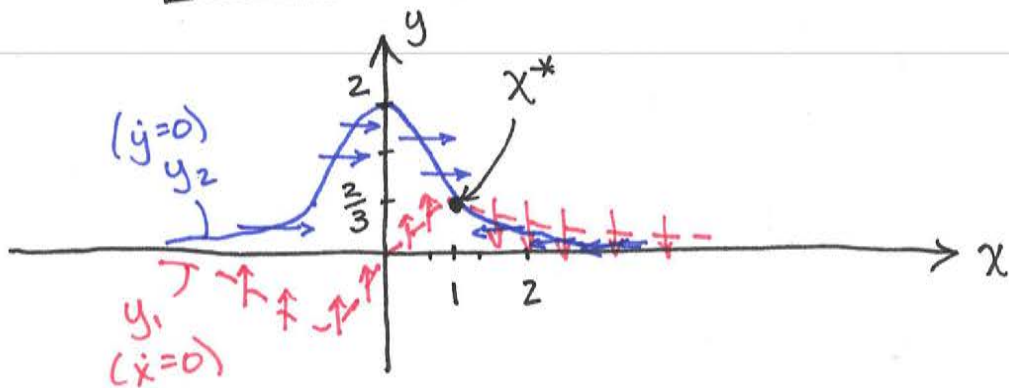
$$\rightarrow \frac{x}{a+x^2} = \frac{b}{a+x^2} \rightarrow x=b$$

$$x^* = \left( b, \frac{b}{a+b^2} \right)$$

Sketch for:

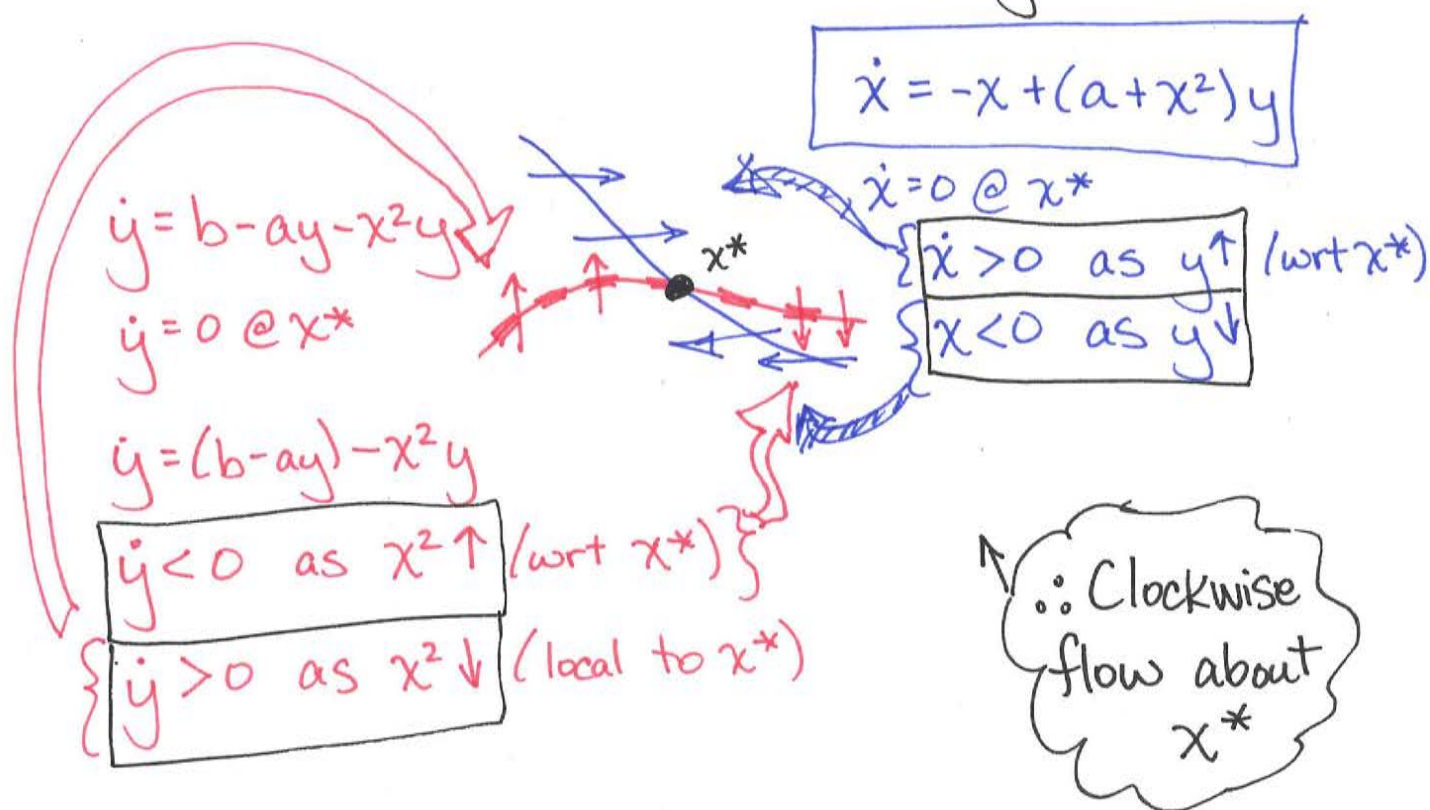
$$a = \frac{1}{2}$$

$$b = 1$$



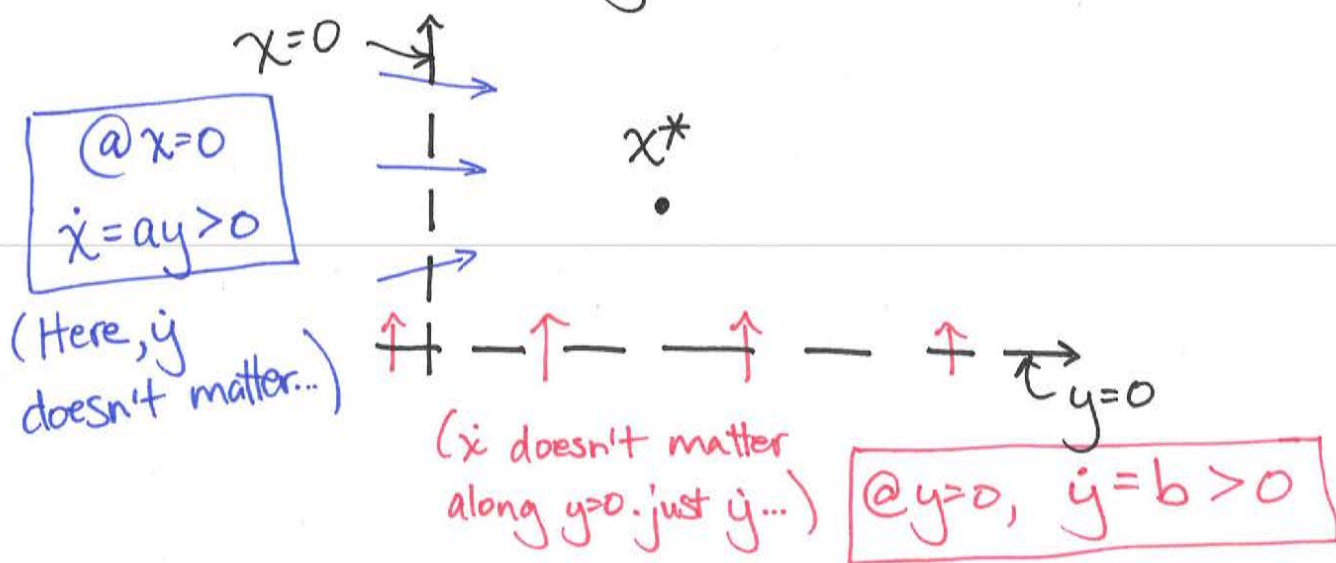
c) How to get arrow directions on nullclines?

Zoom in near  $x^*$  (where  $\dot{x} = \dot{y} = 0$ ).



d) How to get a trapping region?

- Look for lines (or curves) where flow goes strictly "one way" along entire boundary of interest:



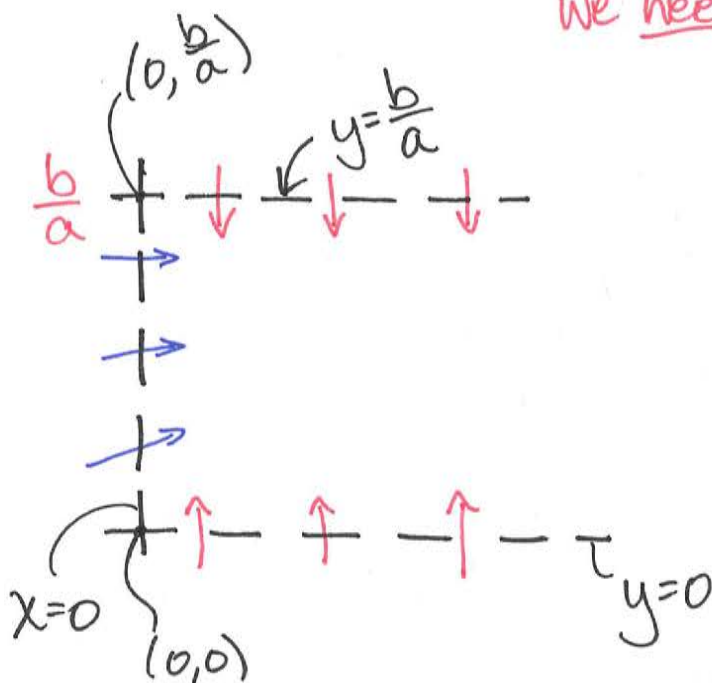


- So far, we have 2 sides.

→ Where can we draw a "roof", such that  $\dot{y} < 0$  is guaranteed (if anywhere)?

$\dot{y} = b - ay - x^2y$  ← for  $x=0$  (y-axis),  
 we need  $\dot{y} = b - ay < 0$

$y > \frac{b}{a}$



- One side left! Note terms cancel out for  $\dot{x} + \dot{y}$ :

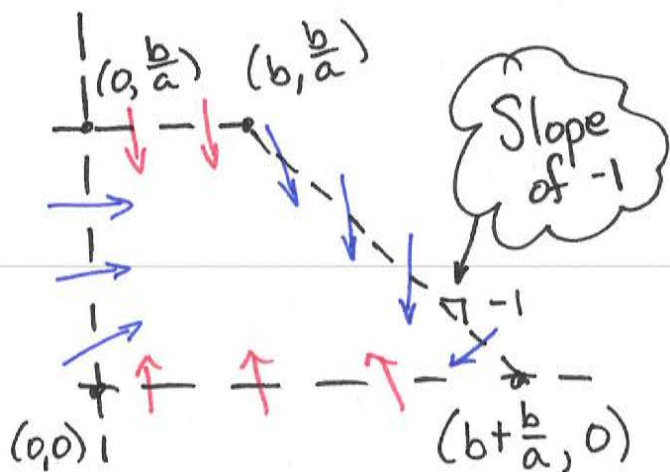
$$\begin{aligned} \dot{x} &= -x + (a+x^2)y \\ \dot{y} &= b - (a+x^2)y \end{aligned}$$

$$\dot{x} + \dot{y} = b - x$$

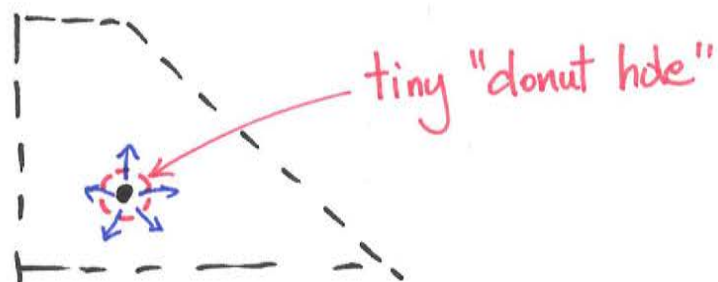


$$\therefore \dot{y} = -\dot{x} \text{ @ } x=b$$

$\dot{y} < -\dot{x} \text{ for } x > b$



• Finally we must excluded the fixed pt  
AND guarantee flow @ this inner bound  
 goes into the TRAP.



→  $x^*$  needs to be an unstable node.

Linearization:  $A = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} = \begin{bmatrix} -1+2xy & a+x^2 \\ -2xy & -a-x^2 \end{bmatrix}$   $\Big|_{x^*}$

$x^* = \left(b, \frac{b}{a+b^2}\right)$ , so  $A = \begin{bmatrix} -1+2\frac{b^2}{a+b^2} & (a+b^2) \\ -2\frac{b^2}{a+b^2} & -(a+b^2) \end{bmatrix}$

$\Delta = a+b^2 > 0$

$\tau = \frac{-b^2 + (2a-1)b^2 + (a+a^2)}{a+b^2}$

$x^*$  unstable REQUIRES  $a$  in the  
 area shown, bounded by  
 $b^2 = \frac{1}{2}(1-2a \pm \sqrt{1-8a})$

