Department of Electrical & Computer Engineering University of California, Santa Barbara ECE 245 Spring 2008 Shynk H.O. #2

# ECE 245 ADAPTIVE FILTER THEORY TENTATIVE COURSE OUTLINE

# **OPTIMAL FILTERING**

Wide-sense stationary signals Wiener-Hopf equation Noncausal Wiener filter Causal Wiener filter Mean-square-error (MSE) expressions

#### PERFORMANCE SURFACE

Natural, translated, and rotated coordinate systems Normal form of the correlation matrix RInterpretation of eigenvalues and eigenvectors Stochastic normal equation Stochastic orthogonality principle

# STEEPEST DESCENT AND NEWTON'S METHOD

Gradient vector and Hessian matrix Stability conditions for convergence One-step convergence Geometric ratio and time constants

#### GRADIENT ESTIMATION

Weight-misadjustment method Perturbation PGradient noise model Misadjustment M

# LEAST-MEAN-SQUARE (LMS) ALGORITHM

Convergence in the mean Convergence of the MSE Stability conditions on the step-size parameter  $\mu$ Misadjustment expressions Modified LMS algorithms

# METHOD OF LEAST SQUARES (LS)

Nonrecursive (block) solution Windowing of the data Deterministic normal equation Deterministic orthogonality principle Minimum sum of squared errors Properties of LS estimates

# RECURSIVE LEAST SQUARES (RLS)

Exponential weighting  $\lambda$ Prewindowed data Matrix inversion lemma Weight and error recursions Initial conditions Convergence in the mean (bias) Convergence in the mean square Sliding window form

#### LINEAR PREDICTION

Forward and backward prediction errors Augmented normal equation Levinson-Durbin recursion Reflection coefficients (time-invariant) Lattice realization Step-up and step-down recursions Correlation properties Joint-process estimation Burg formula

## ADAPTIVE LATTICE FILTERS

Gradient methods Least-squares approach Augmented normal equation: prewindowed form A priori and a posteriori estimation errors Order updates Gain vector, likelihood variable  $\gamma$ Time updates Joint-process estimation Correlation properties

# APPLICATIONS

Linear prediction Adaptive noise canceling System identification Inverse modeling