

Switching circuits: basics and switching speed

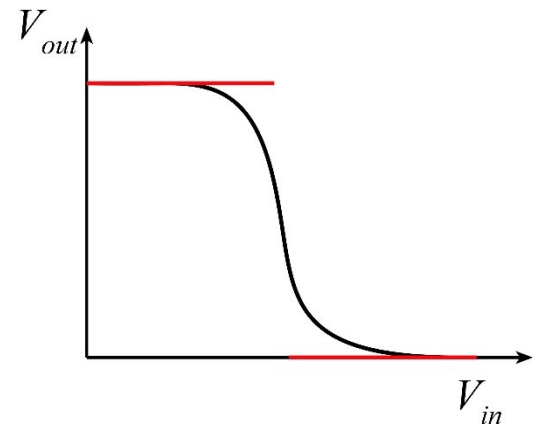
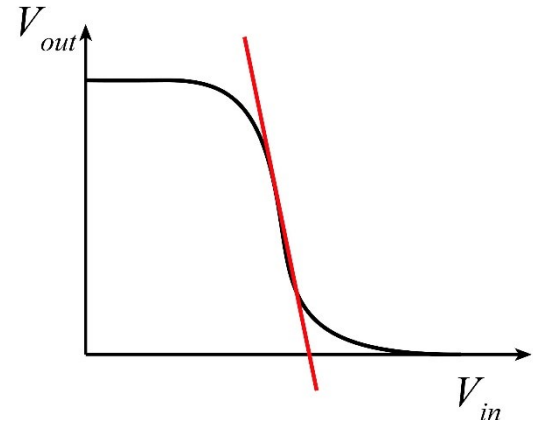
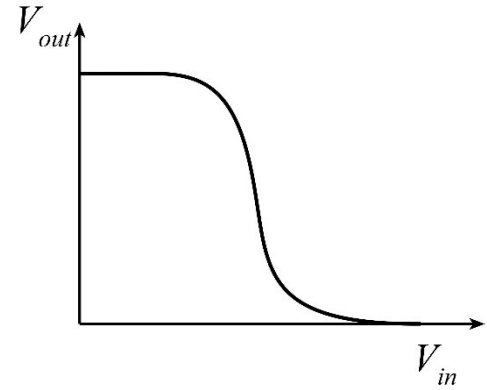
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Amplifiers vs. switching circuits

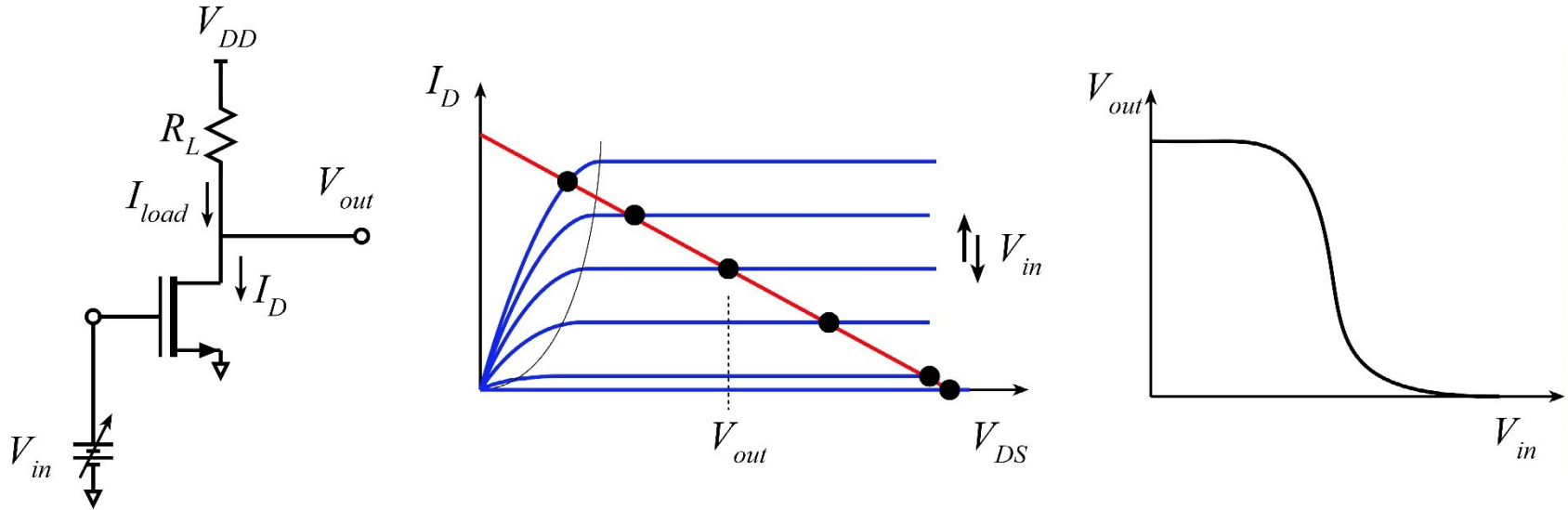
Some transistor circuit might have V_{in} vs. V_{out} characteristics like this:

The characteristics have a nearly linear amplification region:

Plus limiting or clipping regions set by cutoff (minimum current) or "saturation" (minimum voltage)



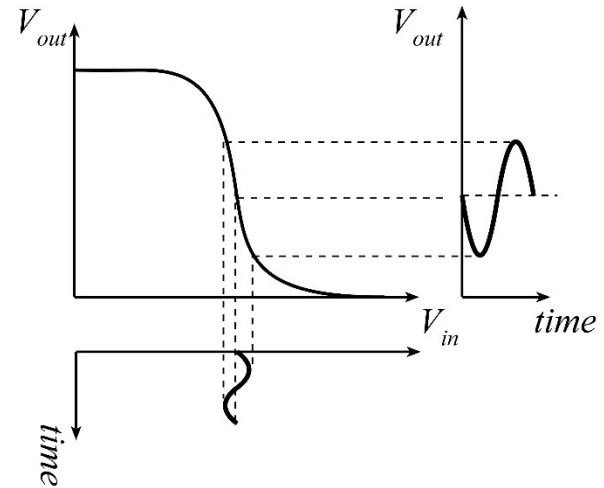
Trivial example: CS stage with resistive load



Here, the lower limit on V_{out} is set by saturation, and the upper limit by cutoff

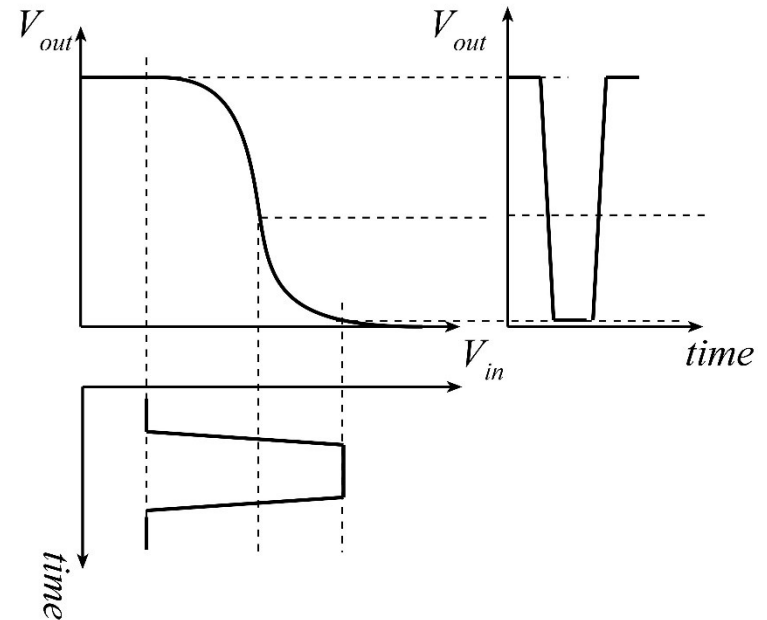
Amplifiers vs. switching circuits

Biased in the linear region,
and with a sufficiently small input,
the circuit is an **amplifier**



But, if the input is large, then the output
switches between the clipping values.

This is a **switching circuit**

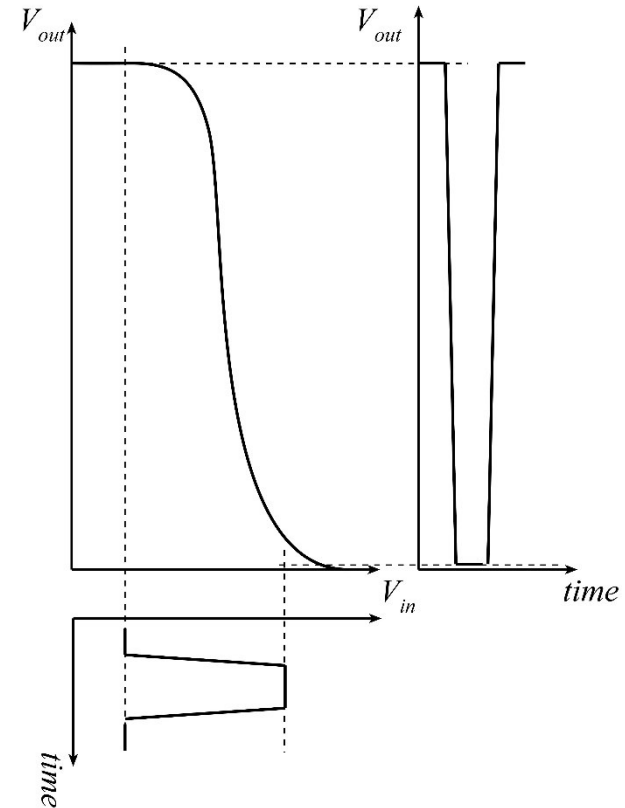
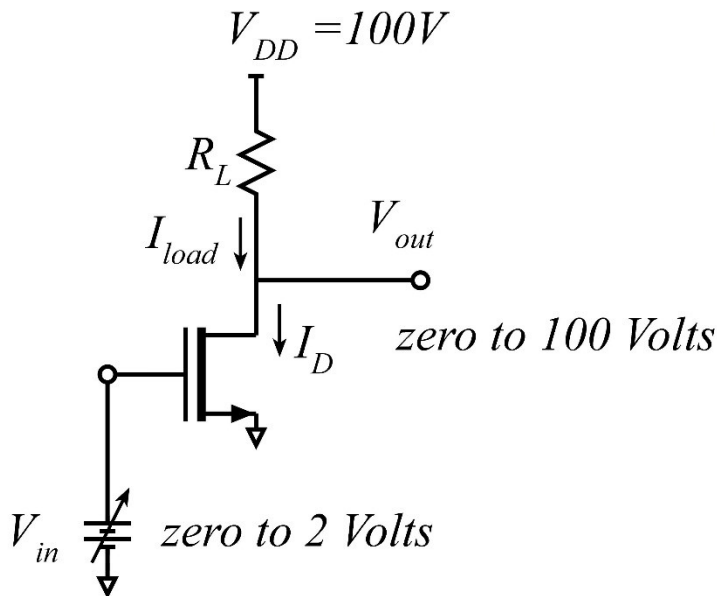


Switching circuits vs. logic gates

Logic gates are a particular *type* of switching circuit

A general switching circuit might have a different range for V_{out} and V_{in} .

...and might not perform *logic*

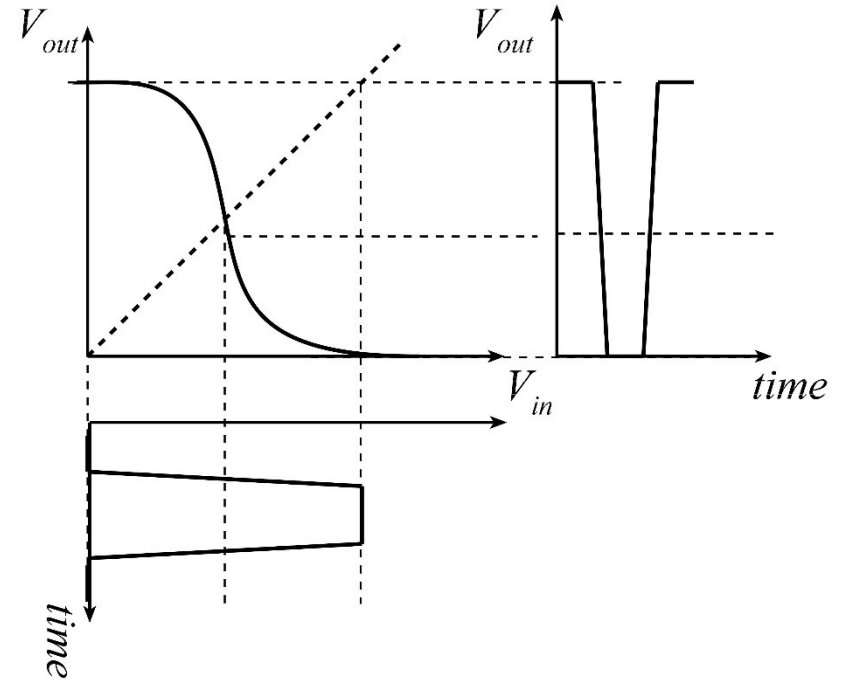


Switching circuits vs. logic gates

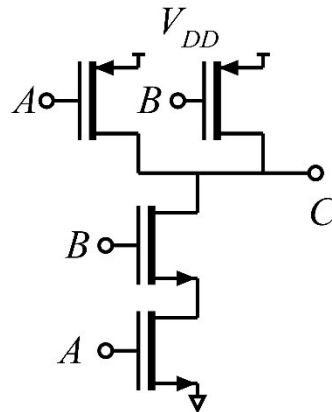
Logic gates are a particular *type* of switching circuit

A logic gate will have the same range for V_{out} and V_{in} .

...and usually has multiple inputs to perform Boolean operations



CMOS NAND gate:



Switching circuits vs. logic gates

Our focus here is on switching circuits, and on calculating
DC $V_{in} - V_{out}$ transfer characteristics
switching risetimes and falltimes

You should have , by now, studied basic logic gates
in other classes

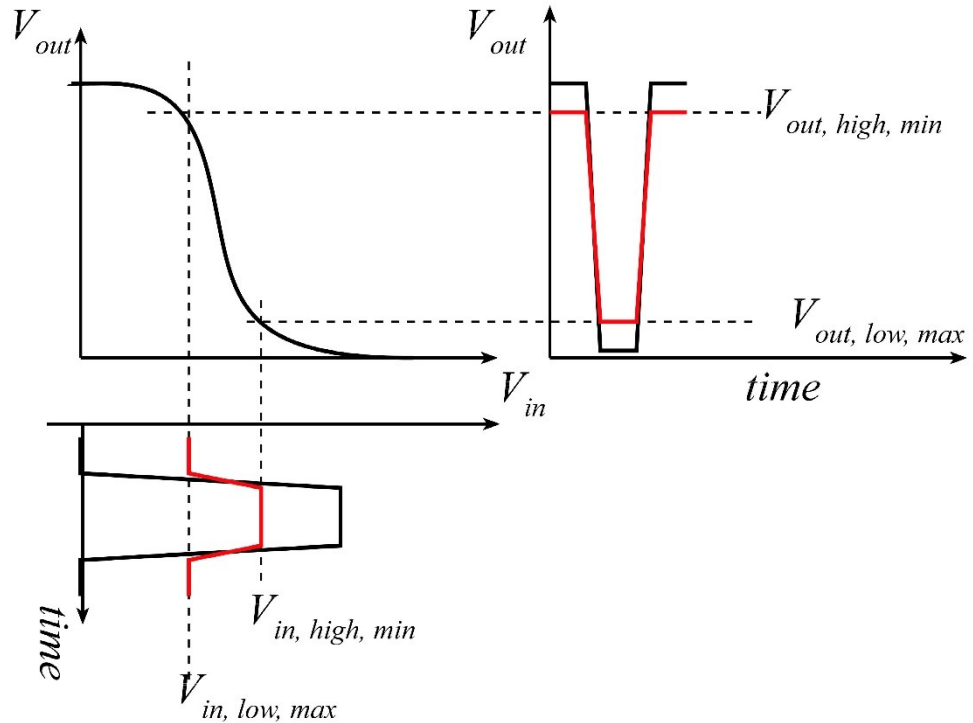
Noise margins

"Noise" margins: tolerance for component variation, EMI

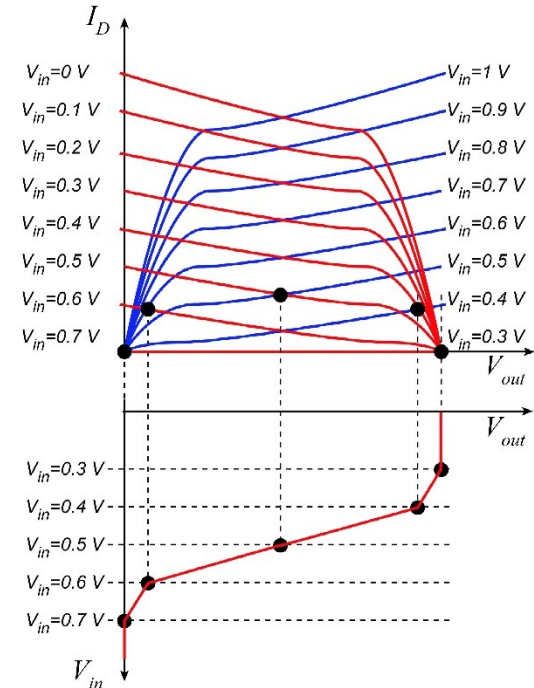
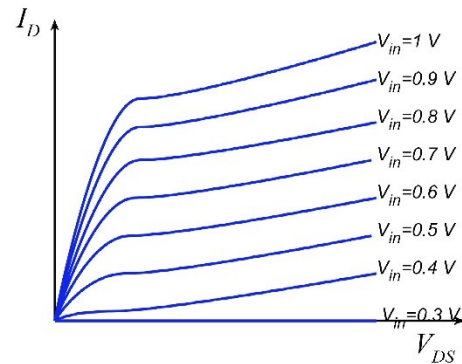
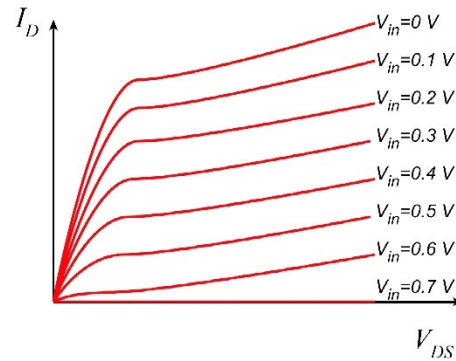
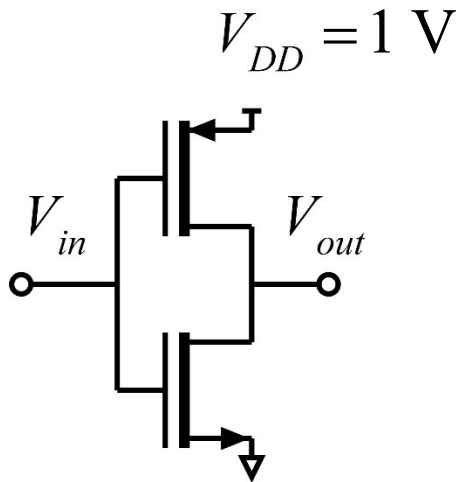
Input low level can vary over a considerable range, yet always produce nearly the same output "high" level

Input high level can vary over a considerable range, yet always produce nearly the same output "low" level

Defining margins precisely is difficult for general switching circuits.
....easier for logic



Another switching circuit: CMOS

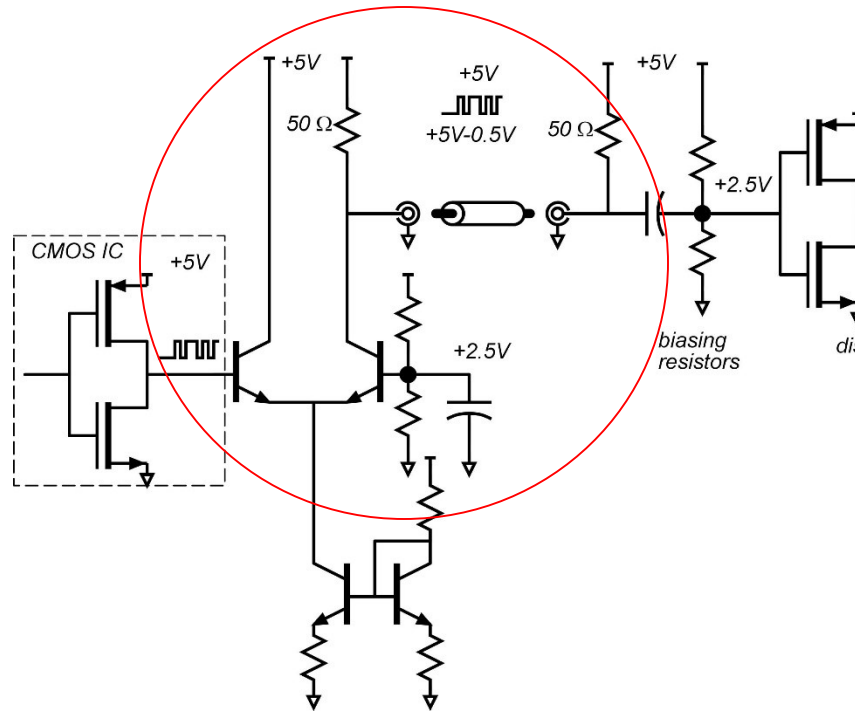


$$I_{D,NFET} = I_{D,PFET} \text{ and } V_{DS,PFET} = V_{DD} - V_{DS,NFET}$$

From these relationships, we obtain the loadline constructions above

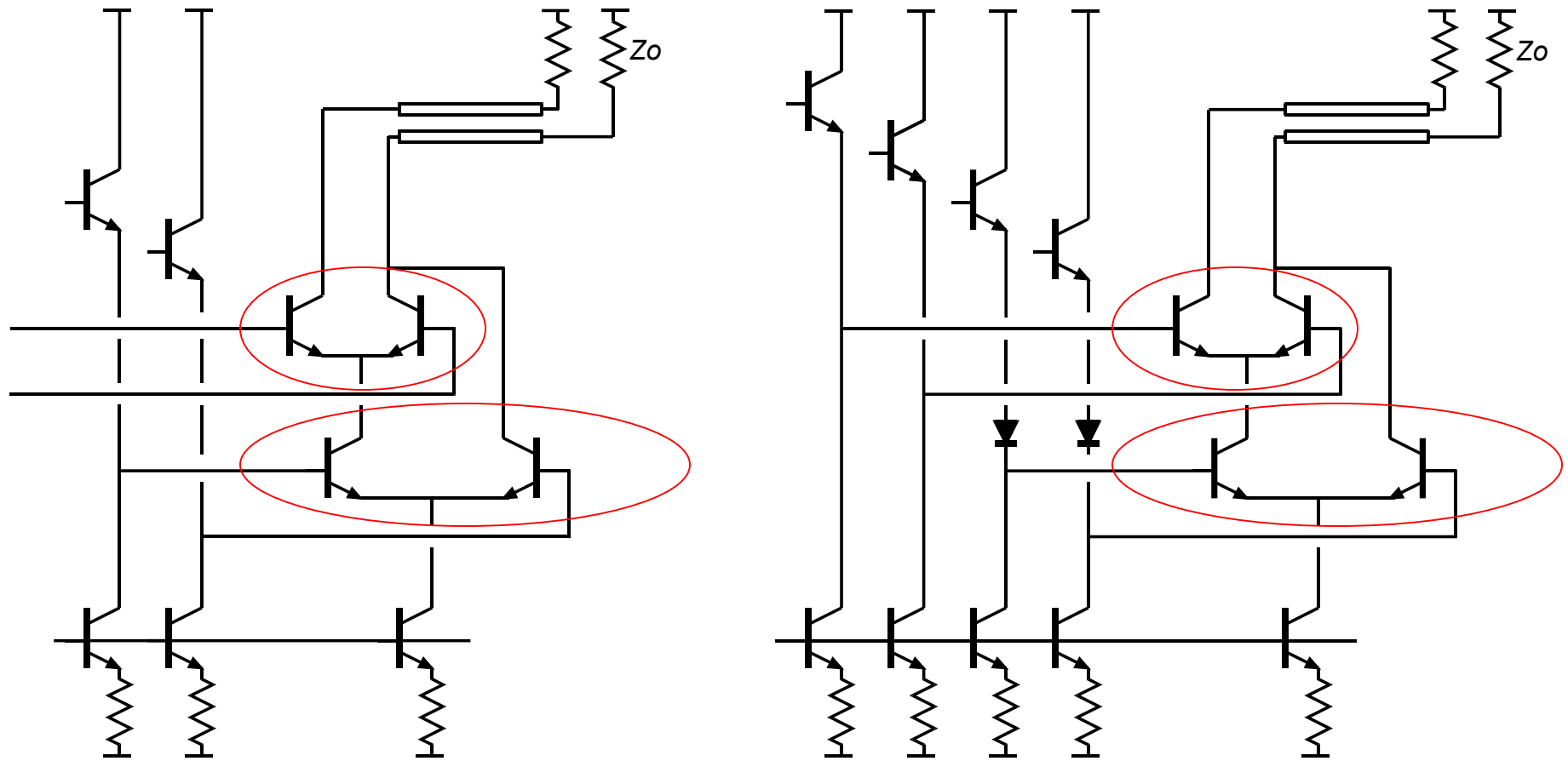
Both the positive and negative clipping limits, hence switched output voltage levels, are set by transistor saturation.

Another switch: emitter-coupled pair



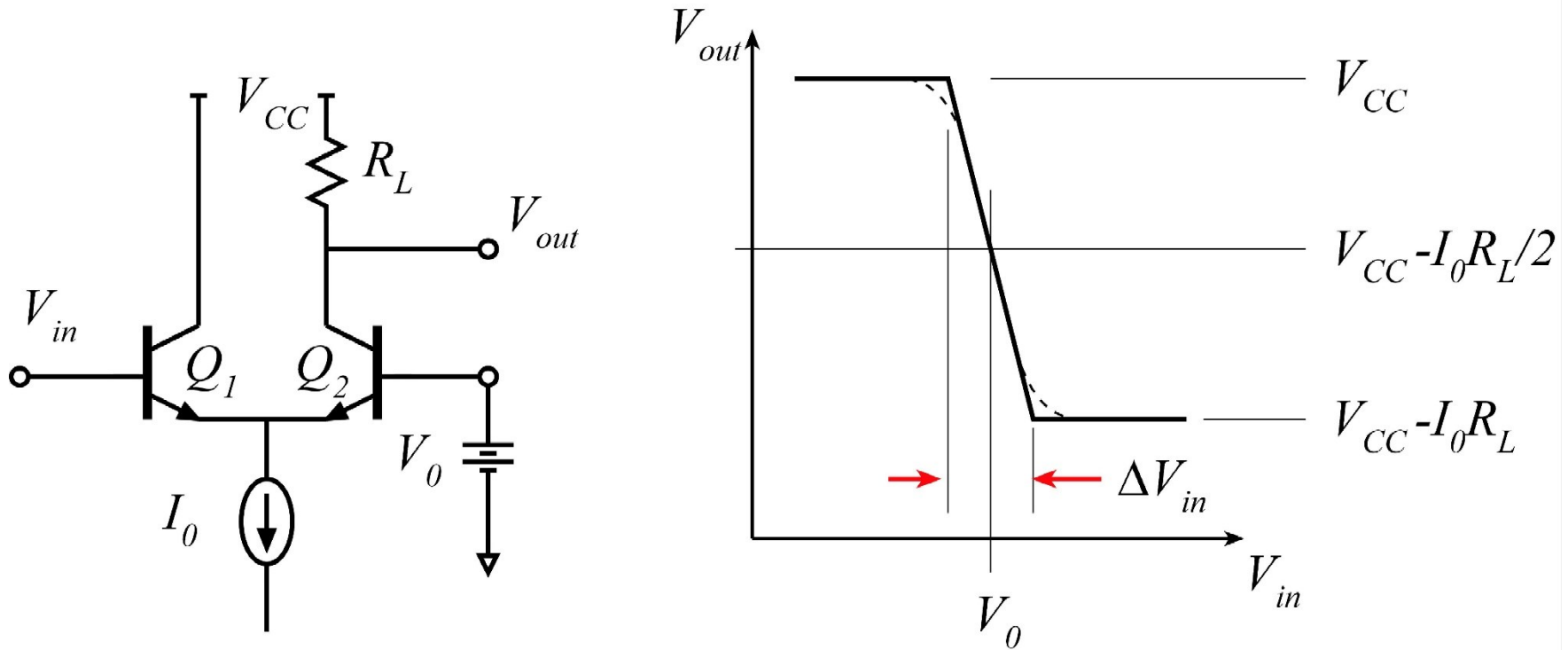
One example of this: the digital 50Ω coaxial cable interface between the PRBS pulse generator and the LED/laser driver in lab project choice #2.

Another switch: emitter-coupled pair



There are also logic families using bipolar differential pairs, current mode logic, left, and emitter coupled logic, right

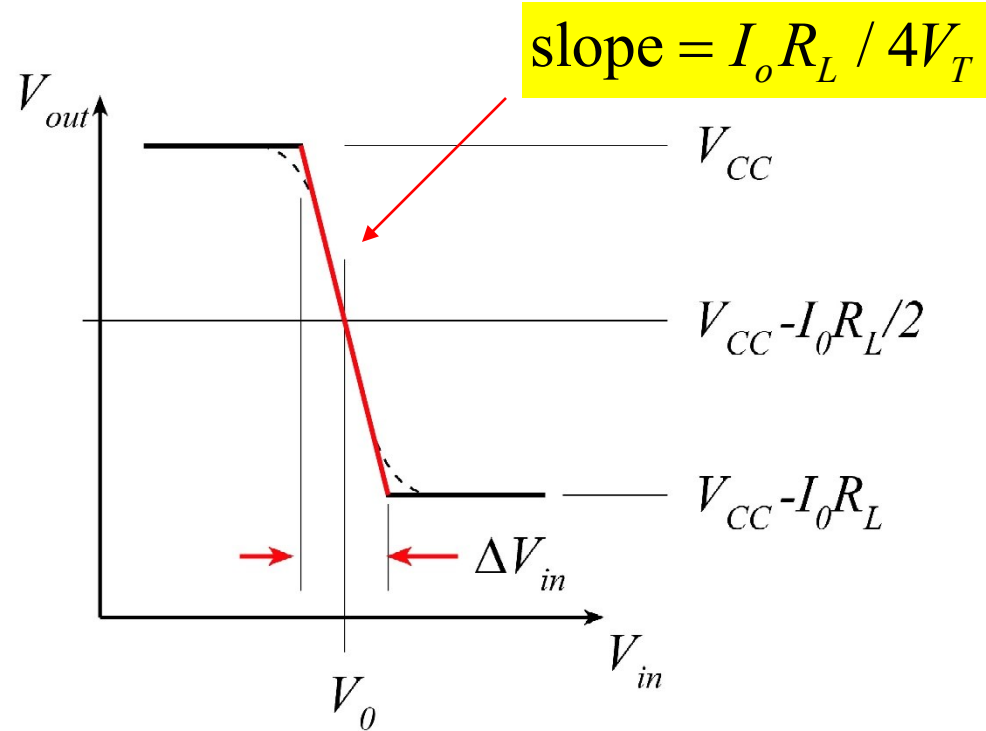
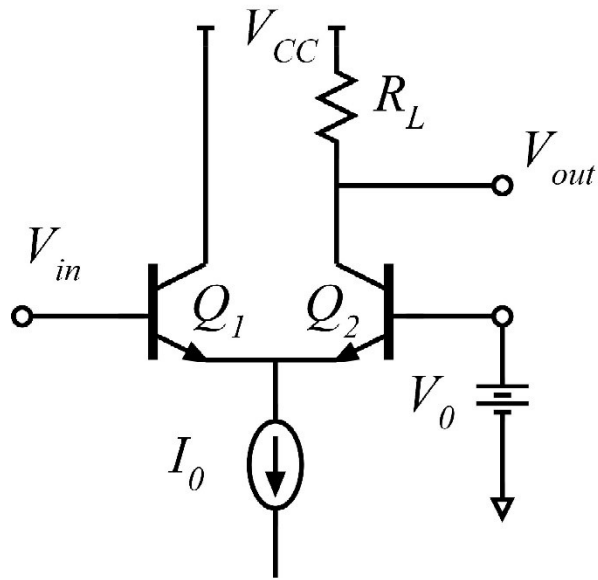
emitter-coupled pair transfer characteristics



The stated levels on the diagram are easily found.

But, how do we find ΔV_{in} ?

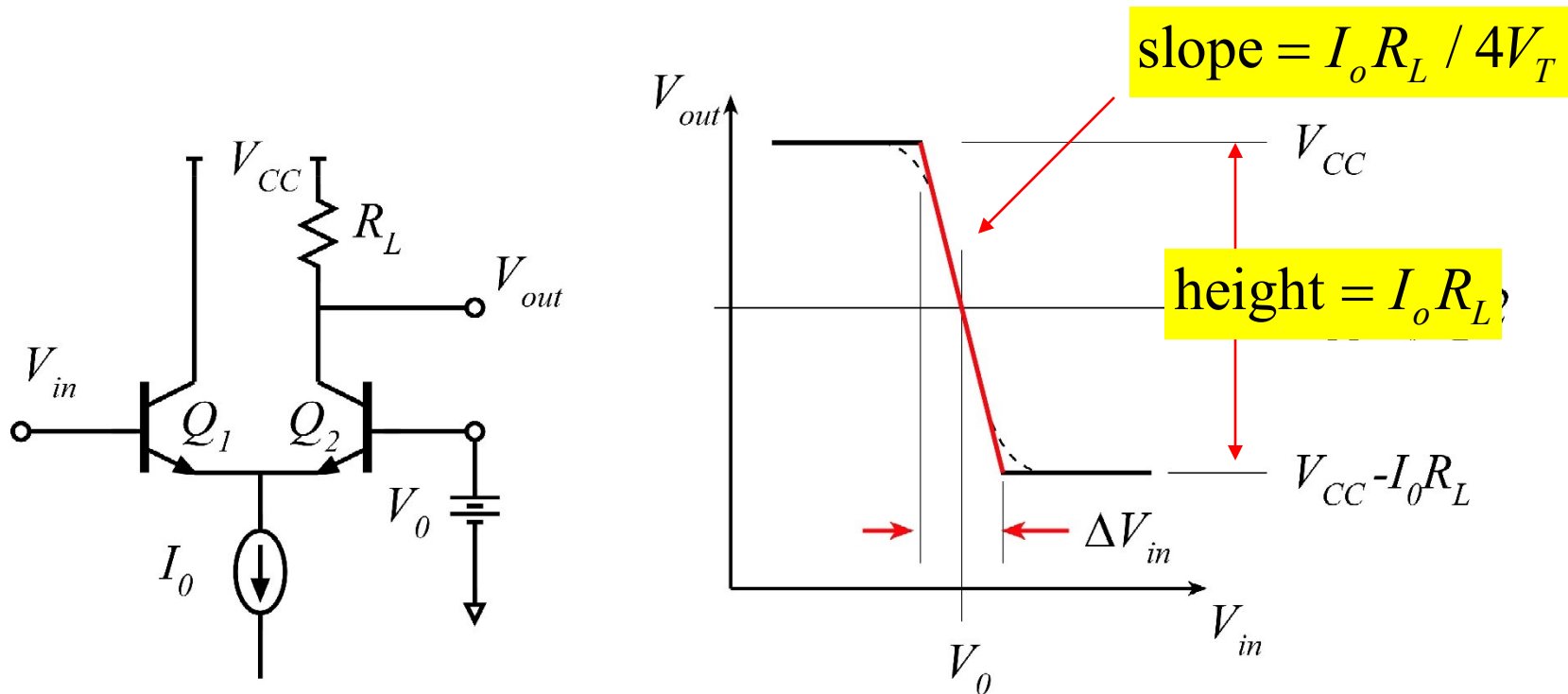
emitter-coupled pair transfer characteristics



DC bias V_{in} at zero Volts, then apply a small signal: what is the gain ?

$$g_m = g_{m1} = g_{m2} = I_o / 2V_T, A_v = \partial V_{out} / \partial V_{in} = g_m R_L / 2 = I_o R_L / 4V_T$$

emitter-coupled pair transfer characteristics



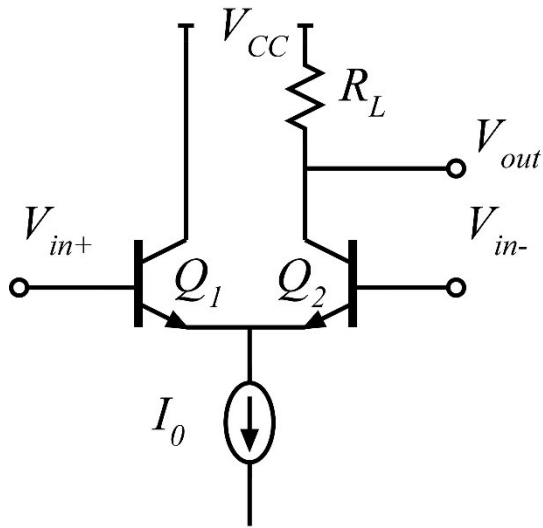
so, the slope of the switching region is $I_o R_L / 4V_T$,

while the output voltage swing is $I_o R_L$,

so the input voltage range must be the ratio of these:

$$\Delta V_{in} = (I_o R_L) / (I_o R_L / 4V_T) = 4V_T = 4kT / q$$

emitter-coupled pair: comments

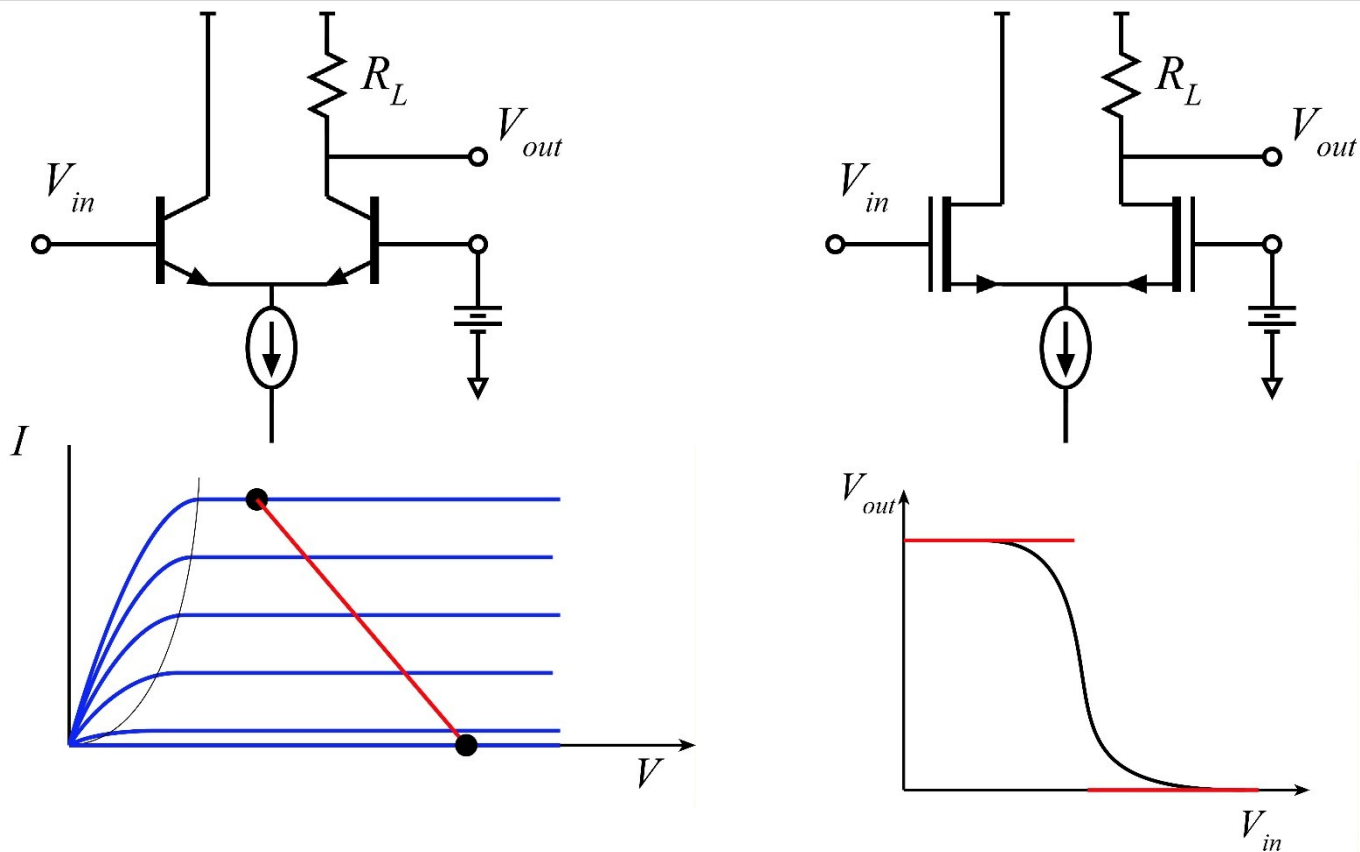


You can repeat this calculation for a differential input \rightarrow different ΔV_{in}

We have assume that Q_1, Q_2 don't saturate over the logic swing.

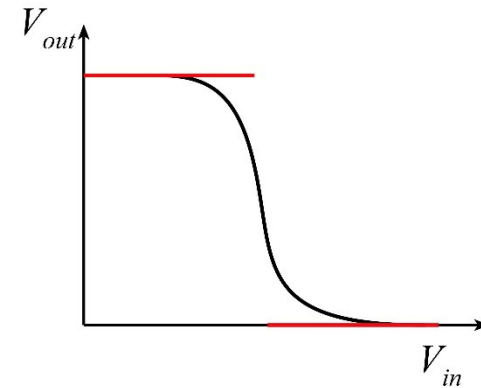
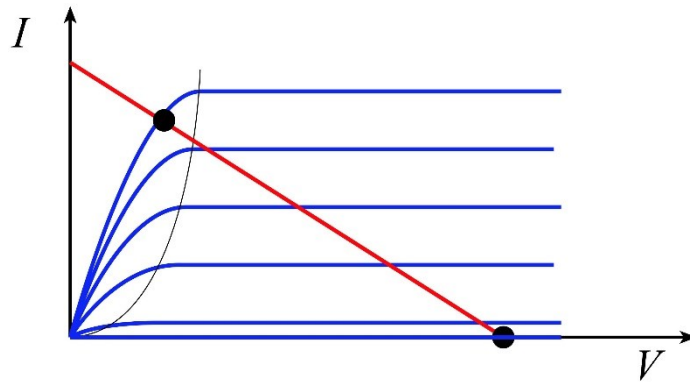
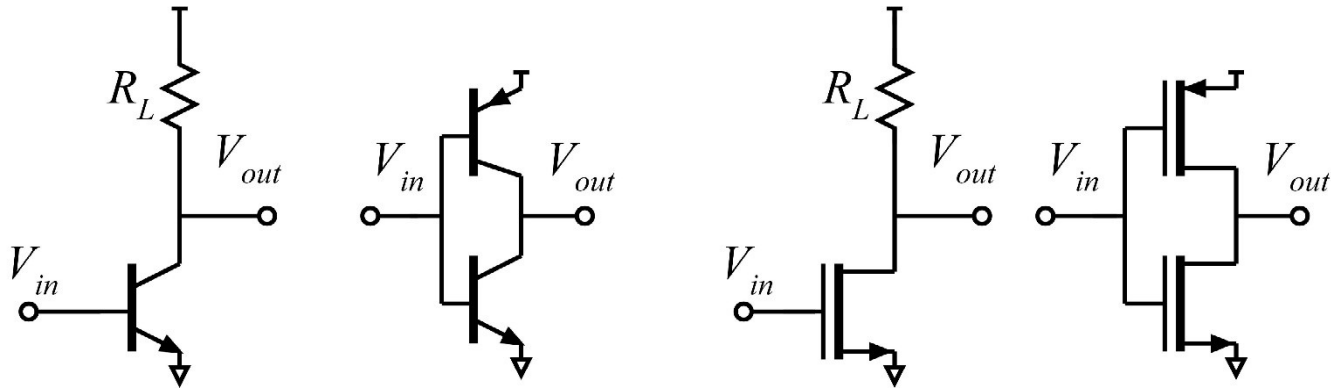
if they do, then this will change the $V_{in} - V_{out}$ characteristics

Limiting mechanisms: current-steering



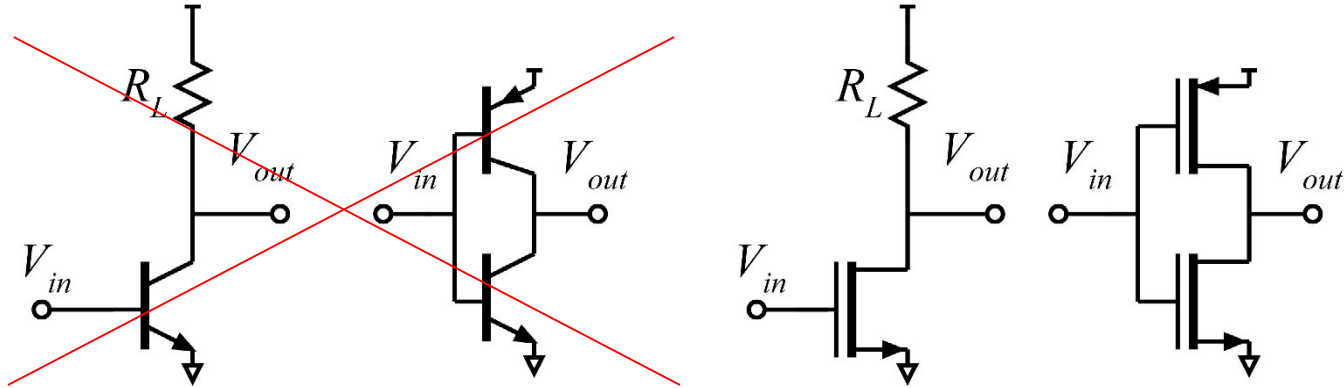
We can design differential current-steering circuits such that both $V_{out,high}$ and $V_{out,low}$ are set by cutoff.

Limiting mechanisms: CS or CE



In these common-source-like and common-emitter-like circuits either or both $V_{out,high}$ and $V_{out,low}$ are set by saturation.

Limiting mechanisms: CS or CE



When BJT's saturate,
they usually store large amounts of minority carrier charge.

Switching speed is then very slow.

With a few exceptions,
saturation is avoided in bipolar switching circuits

Computing risetimes: charge control method

Charge control method: hand estimate switching circuit delay, risetime

-Compute total charge on all capacitors at high Q_{high} and low levels Q_{low}

-Compute voltage on node at high level V_{high} and low level V_{low}

-Compute change in charge $\Delta Q = Q_{high} - Q_{low}$ and voltage $\Delta V = V_{high} - V_{low}$

-If node is charged by constant current I , then charging is linear

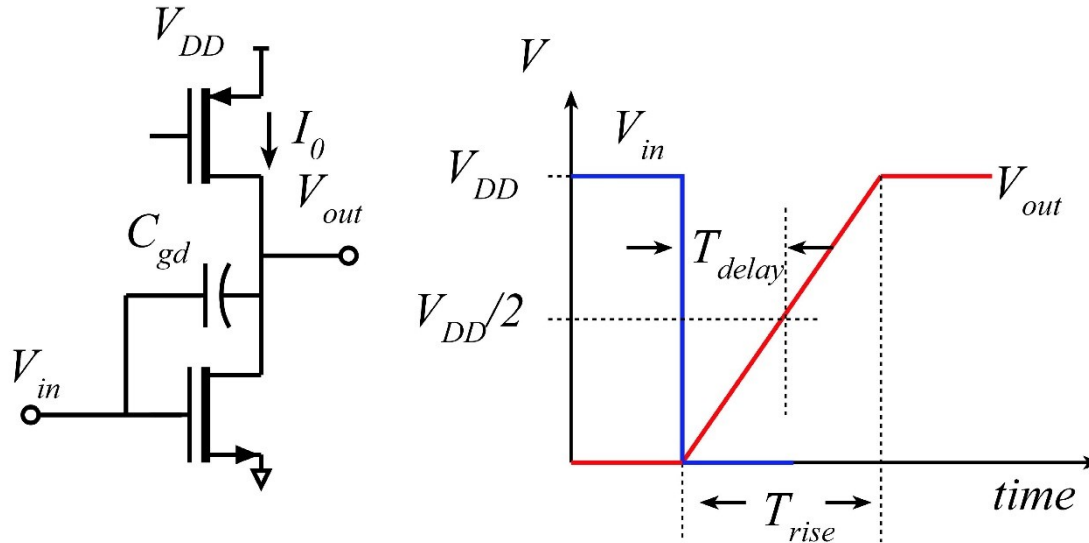
$$T_{rise/fall} = \Delta Q / I \text{ and } T_{delay} = T_{rise/fall} / 2$$

-If node is charged through resistance R , then charging is exponential

Equivalent capacitance $C = \Delta Q / \Delta V$, time constant $\tau = RC$

$$T_{rise/fall} = 2.2\tau \text{ and } T_{delay} = \tau \ln(2)$$

Charging through a current source



The input voltage falls suddenly, turning the FET off.

Let's ignore, just for now,

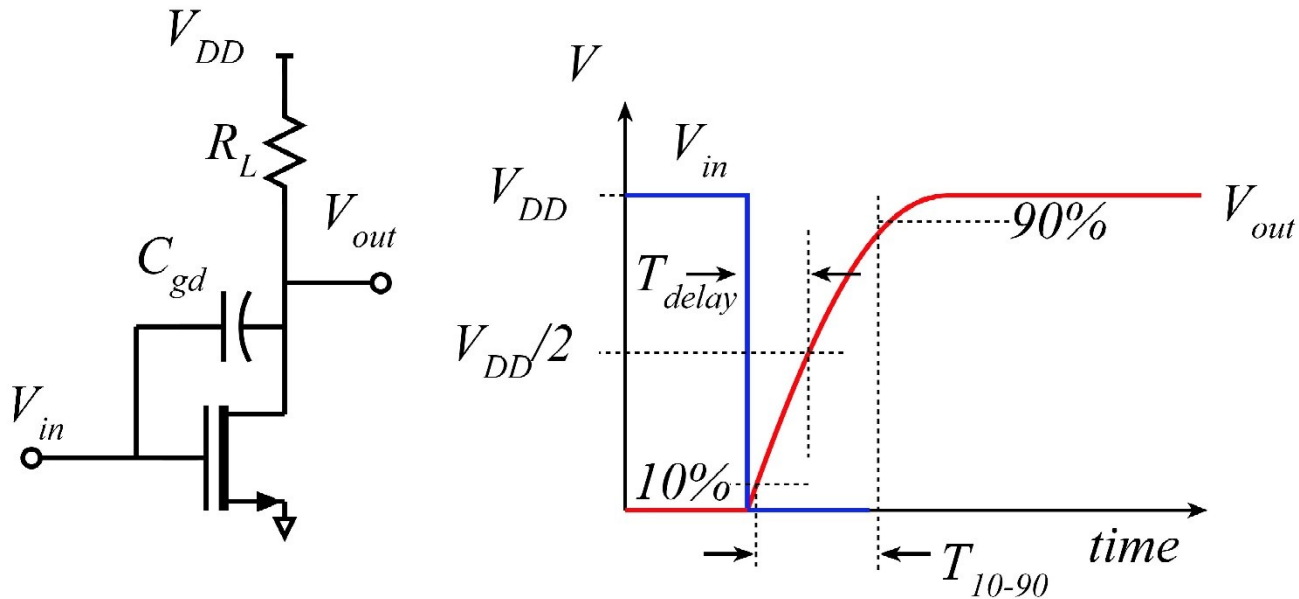
the PFET knee voltage; treat as current source.

Now, constant current charges capacitance.

Charging is linear

$$T_{rise/fall} = \Delta Q / I_0 \quad \text{and} \quad T_{delay} = T_{rise/fall} / 2$$

Charging through a resistance



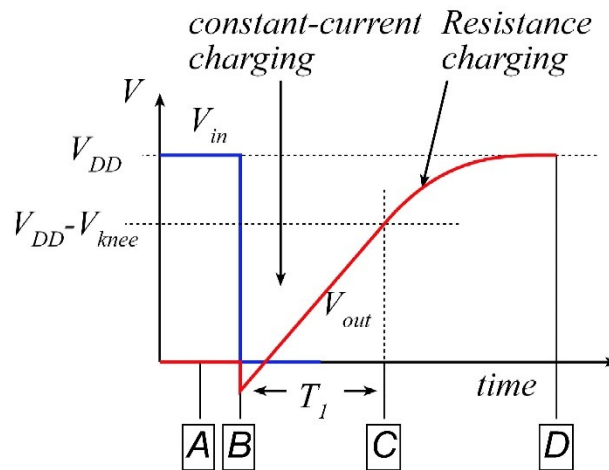
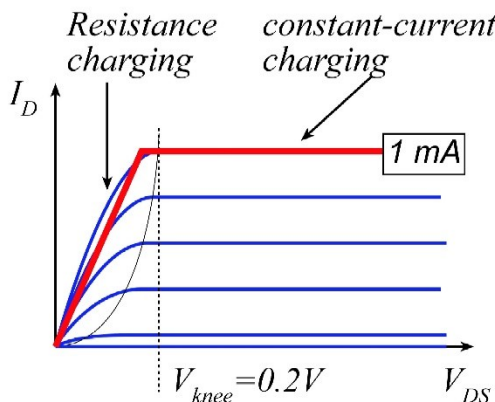
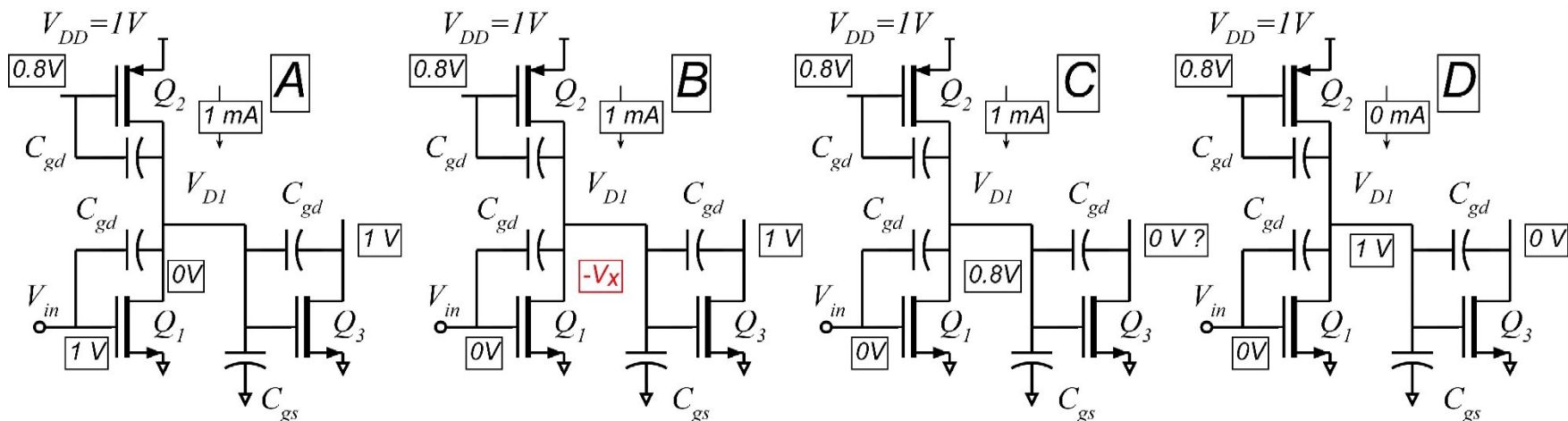
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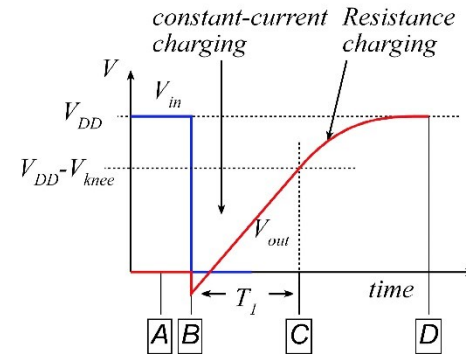
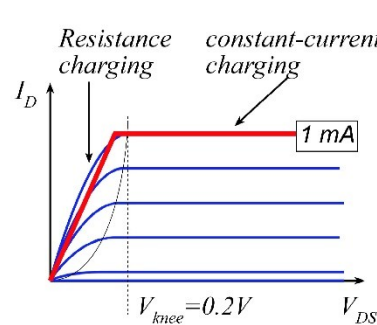
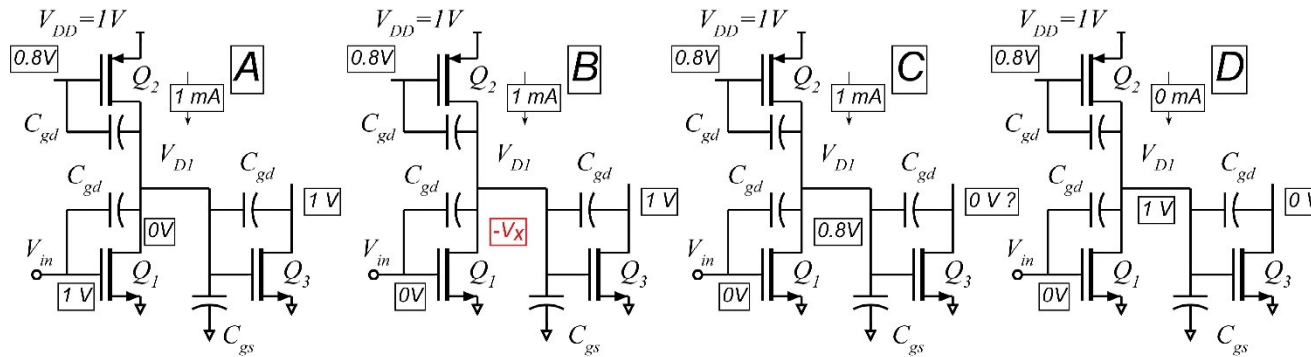
Example: Waveform at Q1 drain



V_{in} switches at $t = 0$.

We will estimate $V_{D1}(t)$.

Example: Waveform at Q1 drain



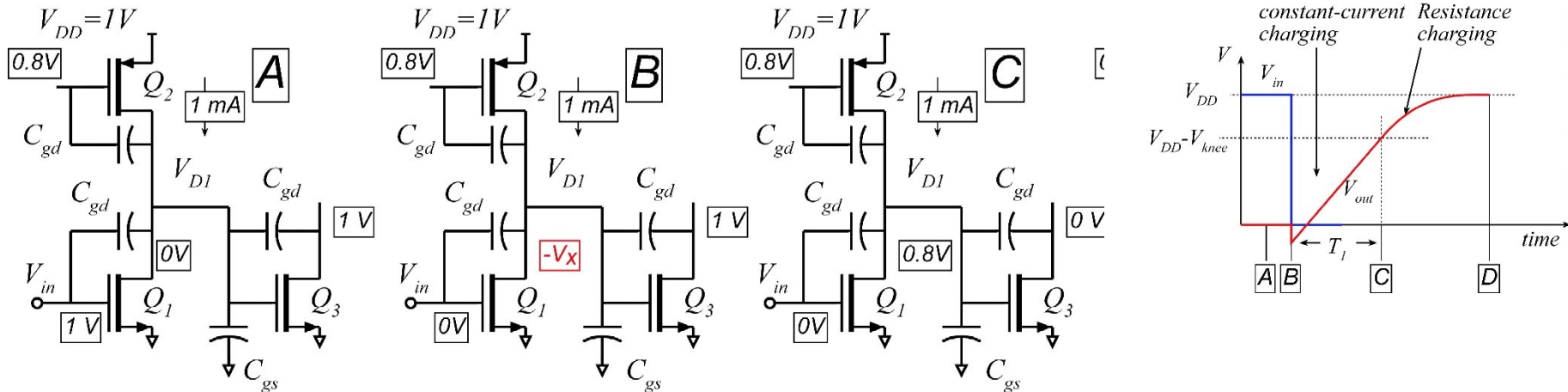
Note:

- 1) $V_{D1}(t)$ initially swings negative: $V_{in}(t)$ couples to $V_{D1}(t)$ through a capacitive voltage divider between C_{gd1} and $(C_{gd2}, C_{gd3}, C_{gs3})$
- 2) $V_{D1}(t)$ then charges towards +1V.

Between $V_{D1} = 0V$ and $0.8V$, Q_2 is a constant-current source

Between $V_{D1} = 0.8V$ and $1V$, Q_2 acts as a resistance (saturation)

Example: Waveform at Q1 drain



Switching time between A and C: 1st part: charging to 0.8V

change in charge in:

$$C_{gd1}: @ A: Q = -1V \cdot C_{gd1}, @ C: Q = 0.8V \cdot C_{gd1}, \Delta Q = 1.8V \cdot C_{gd1}$$

$$C_{gd2}: @ A: Q = -0.8V \cdot C_{gd2}, @ C: Q = 0V \cdot C_{gd2}, \Delta Q = 0.8V \cdot C_{gd2}$$

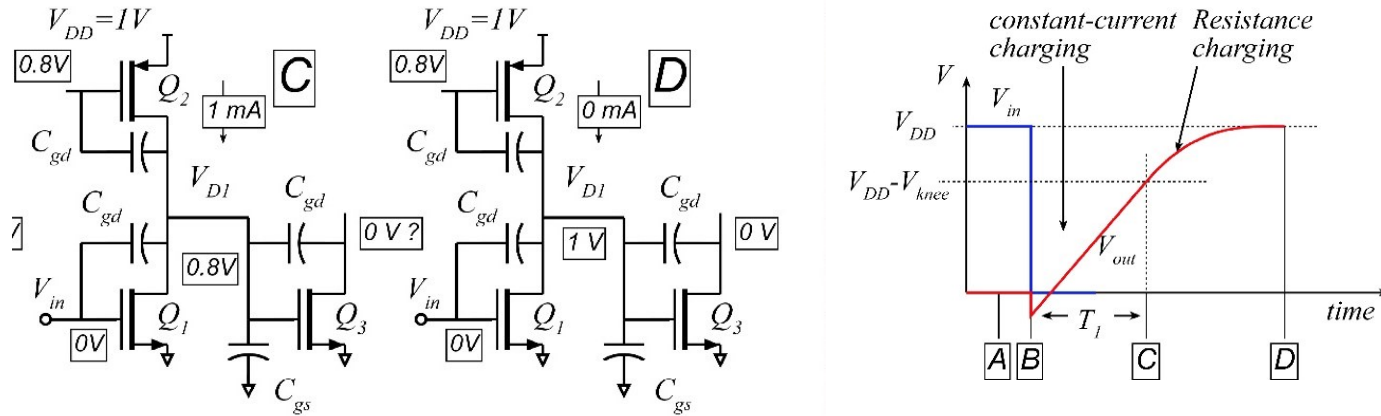
$$C_{gd3}: @ A: Q = -1V \cdot C_{gd3}, @ C: Q = 0.8V \cdot C_{gd3}, \Delta Q = 1.8V \cdot C_{gd3}$$

$$C_{gs3}: @ A: Q = 0V \cdot C_{gs3}, @ C: Q = 0.8V \cdot C_{gs3}, \Delta Q = 0.8V \cdot C_{gs3}$$

Time for drain of Q1 to charge to 0.8V:

$$T_1 = (1.8V \cdot C_{gd1} + 0.8V \cdot C_{gd2} + 1.8V \cdot C_{gd3} + 0.8V \cdot C_{gs3}) / 1mA$$

Example: Waveform at Q1 drain



Switching time between C and D: 2nd part: charging from 0.8V towards 1V

$$C_{gd1}: @ C: Q = 0.8 \cdot C_{gd1}, @ D: Q = 1V \cdot C_{gd1}, \Delta Q = 0.2V \cdot C_{gd1}$$

$$C_{gd2}: @ C: Q = 0V \cdot C_{gd2}, @ D: Q = 0.2V \cdot C_{gd2}, \Delta Q = 0.2V \cdot C_{gd2}$$

$$C_{gd3}: @ C: Q = 0.8V \cdot C_{gd3}, @ D: Q = 1V \cdot C_{gd3}, \Delta Q = 0.2V \cdot C_{gd3}$$

$$C_{gs3}: @ C: Q = 0.8V \cdot C_{gs3}, @ D: Q = 1V \cdot C_{gs3}, \Delta Q = 0.2V \cdot C_{gs3}$$

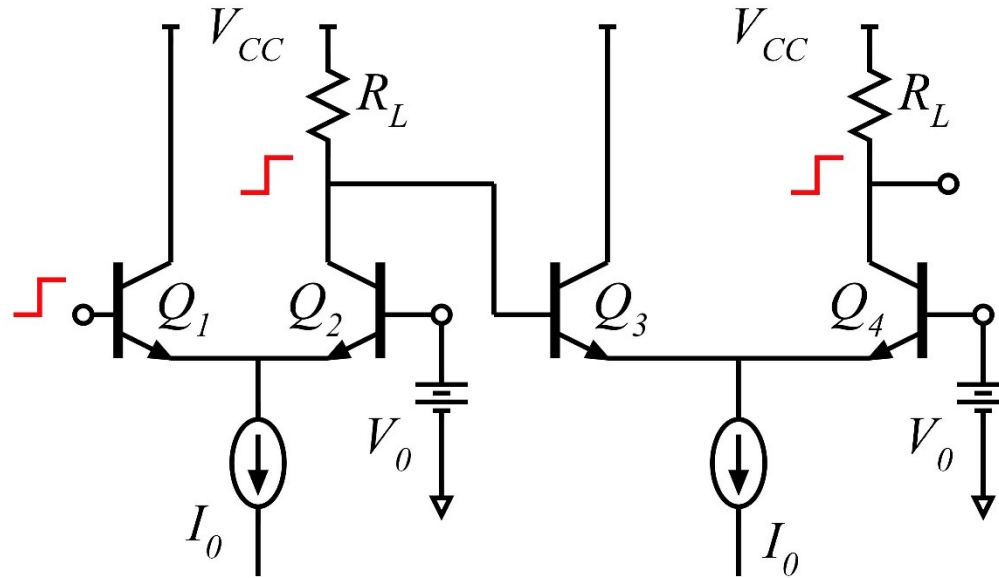
Effective capacitance :

$$C_{eff} = (0.2V \cdot C_{gd1} + 0.2V \cdot C_{gd2} + 0.2V \cdot C_{gd3} + 0.2V \cdot C_{gs3}) / 0.2V = \dots$$

$$\text{Time constant } \tau = R_{DS,sat} C_{eff} = R_{DS,sat} (C_{gd1} + C_{gd2} + C_{gd3} + C_{gs3})$$

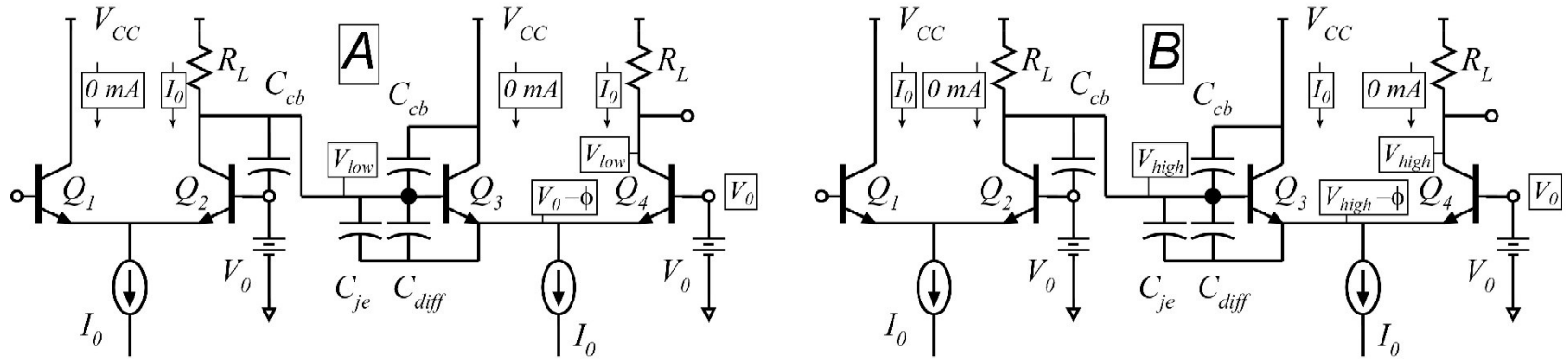
$$\text{Exponential charging: } V_{D1}(t) = 0.8V + (1V - 0.8V)(1 - \exp((t - T_1) / \tau))$$

Example: bipolar differential switch

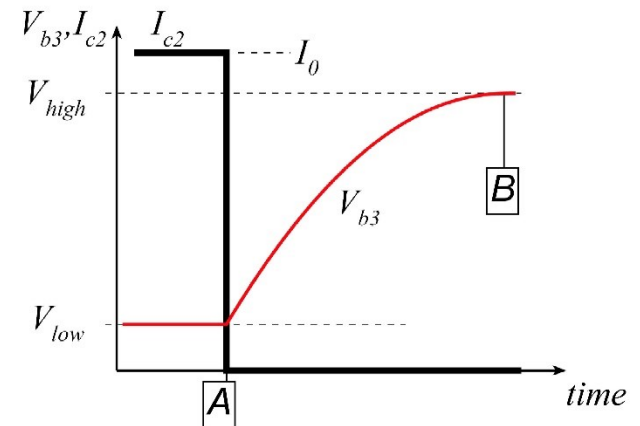


Let us calculate the risetime at the base of Q_3

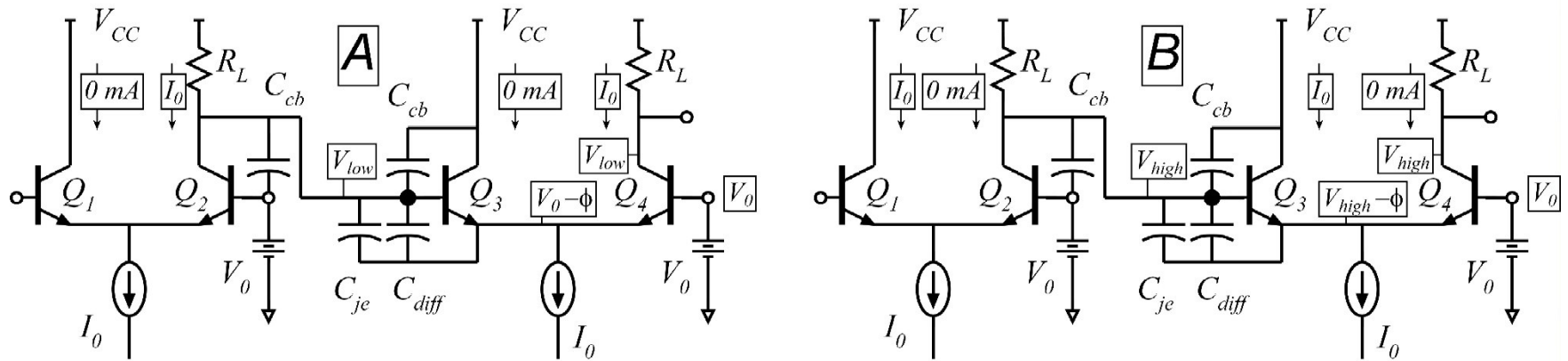
Example: bipolar differential switch



Let us calculate the risetime at the base of Q_3
 Times are relative to the time at which
 the collector current of Q_2 switches to zero.



Example: bipolar differential switch



Switching time between A and B:

change in charge in:

$$C_{cb2}: \text{ @ A: } Q = V_{low} \cdot C_{cb2} \quad , \quad \text{ @ B: } Q = V_{high} \cdot C_{cb2}, \quad \Delta Q = (V_{high} - V_{low}) \cdot C_{cb2}$$

$$C_{cb3}: \text{ @ A: } Q = (V_{low} - V_{CC}) \cdot C_{cb3} \quad , \quad \text{ @ B: } Q = (V_{high} - V_{CC}) \cdot C_{cb3}, \quad \Delta Q = (V_{high} - V_{low}) \cdot C_{cb3}$$

$$C_{je2}: \text{ @ A: } Q = (V_{low} - V_0 + \phi) \cdot C_{je2} \quad , \quad \text{ @ B: } Q = (V_{high} - V_{high} + \phi) \cdot C_{je2}, \quad \Delta Q = (V_0 - V_{low}) \cdot C_{je2}$$

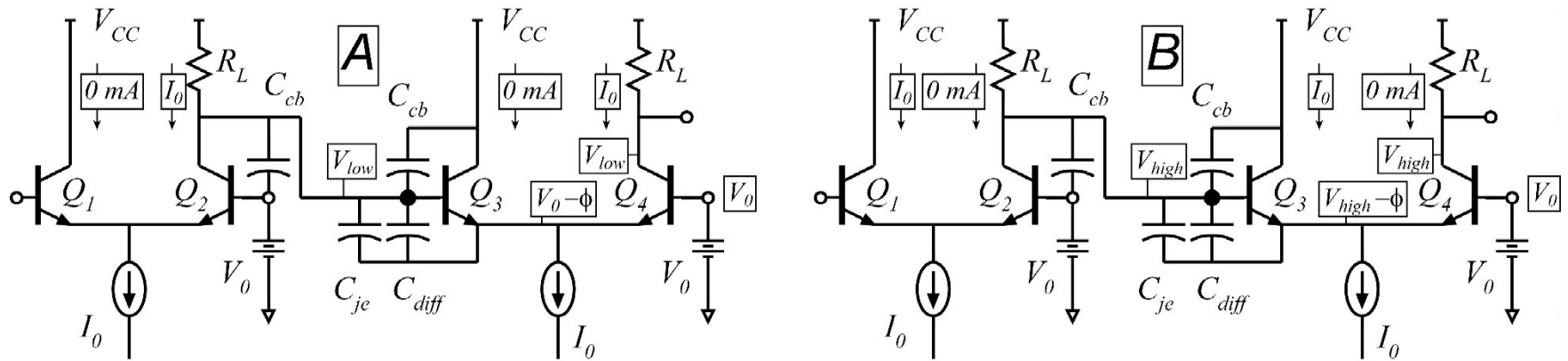
$$C_{diff2}: \text{ @ A: } Q = 0 \text{ mA} \cdot \tau_{f2} \quad , \quad \text{ @ B: } Q = I_0 \cdot \tau_{f2}, \quad \Delta Q = I_0 \cdot \tau_{f2}$$

Effective capacitance:

$$C_{eff} = \Delta Q / (V_{high} - V_{low})$$

$$= \left((V_{high} - V_{low}) \cdot C_{cb2} + (V_{high} - V_{low}) \cdot C_{cb3} + (V_0 - V_{low}) \cdot C_{je2} + I_0 \cdot \tau_{f2} \right) / (V_{high} - V_{low})$$

Example: bipolar differential switch



Effective capacitance:

$$C_{eff} = C_{cb2} + C_{cb3} + C_{je2} \frac{V_0 - V_{low}}{V_{high} - V_{low}} + \frac{I_0 \cdot \tau_{f2}}{V_{high} - V_{low}} \text{ but } V_{high} - V_{low} = I_0 R_L$$

Charging time constant:

$$\tau_{charge} = R_L C_{eff} = R_L C_{cb2} + R_L C_{cb3} + R_L C_{je2} \frac{V_0 - V_{low}}{V_{high} - V_{low}} + \tau_{f2}$$

Voltage waveform:

$$V_{b3}(t) = V_{low} + (V_{high} - V_{low})(1 - \exp(-t / \tau_{charge}))$$

Limitations of charge control

1) the method is very approximate

2) We do not predict the detailed shape of the switching waveform
More detailed analysis can find secondary switching transients at one or more points within the overall waveform. In some cases, spikes are produced. This is more advanced material