Exercise 1 (Switched server). Consider the following switched server example described in Lecture #1. Assume that $\delta > 0$ and $r > r_1, r_2$.

1. For what values of $r_1$, $r_2$, $r$, and $\delta$ do the queues grow unbounded and for what values are they bounded?

2. Consider the case $r_1 = r_2 = 1$, $r = 3$, $\delta = .5$. Compute the reachable set when the hybrid system starts with the queue 1 feeding the buffer and the continuous state in the following set

$$\mathcal{S}_0 := \{(x_1, x_2, x_3) : x_1, x_2 \in [1, 2]\},$$

where $x_3$ denotes the continuous state used to implement the setup time. Please provide your answer graphically by drawing the reachable region in the $x_1$-$x_2$ for each discrete mode. No need to represent the reachable values for $x_3$.

3. Does the reachability algorithm always terminate for this system? \(\square\)

Exercise 2 (Congestion control). Consider the additive increase/multiplicative decrease congestion controller described in Lecture #9 (example #7).
Depending on the values of $a$ and $m$, three distinct steady-state regimens may arise: the one considered in class for which the queue does not become empty, another one for which the queue empties periodically, and a third one (usually known as “congestion collapse”) for which the hybrid system does not have a global solution.

1. Determine the values of the parameters $a$ and $m$ that lead to each regimen (as a function of $q_{\text{max}}$ and $B$).

2. Determine the average sending rates $r$ for the two regimens in which steady-state solutions exist.

3. Which of the previous two regimens leads to a larger average sending rate $r$?

   Provide guidelines for the choice of the maximum buffer size $q_{\text{max}}$ to maximize the average sending rate.