

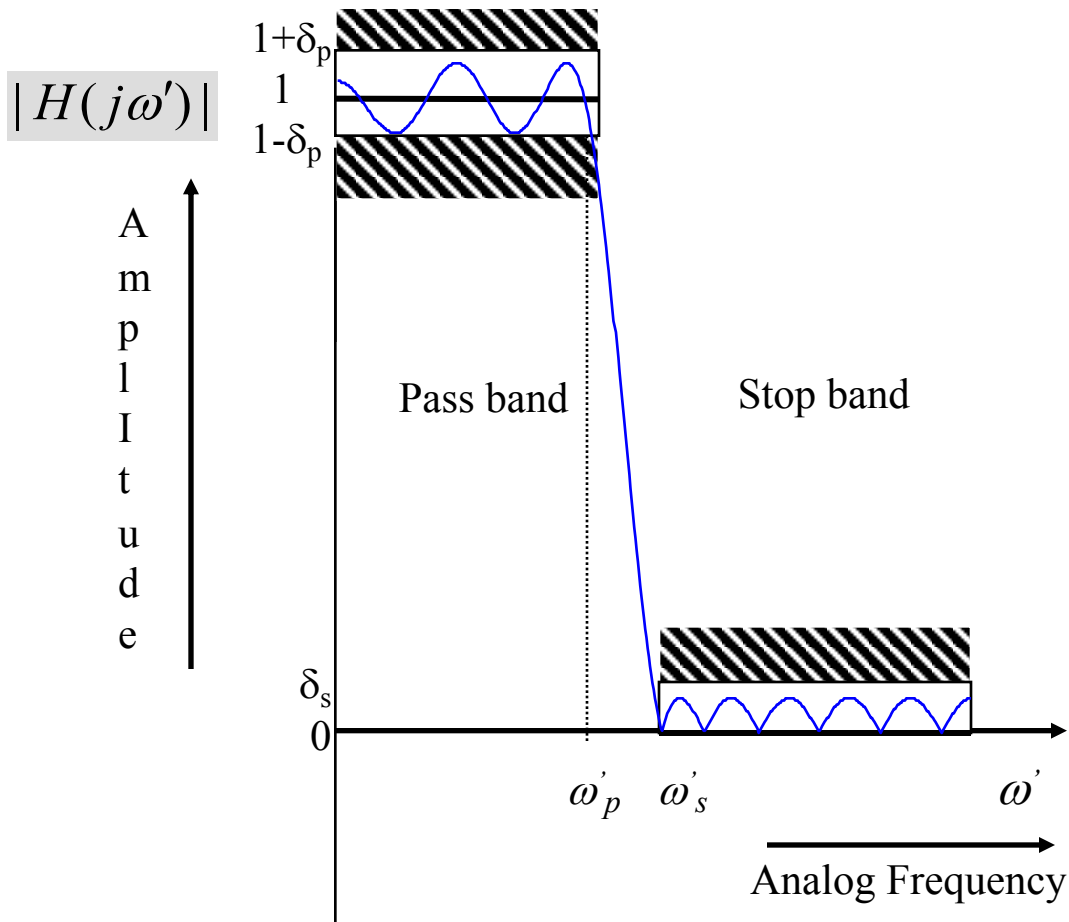
Analog Filters

(I)

Introduction

Yogananda Isukapalli

Analog Filter Specifications



$$1 - \delta_p \leq |H(j\omega')| \leq 1 + \delta_p \text{ for } |\omega'| \leq \omega'_p,$$

$$|H(j\omega')| \leq \delta_s \text{ for } \omega'_s \leq |\omega'| \leq \infty,$$

$$\alpha_p = -20 \log_{10}(1 - \delta_p) \text{ dB},$$

$$\alpha_s = -20 \log_{10}(\delta_s) \text{ dB},$$

Where α_p and α_s are the peak pass band ripple and minimum stop band attenuation in dB respectively

Review :



$$y(t) = \sum_{k=0}^N a_k \frac{d^k x(t)}{dt^k} + \sum_{k=0}^M b_k \frac{d^k y(t)}{dt^k}$$

Example : $a_1 = 1$ and all other “a’s” and “b’s” are zero.

$$y(t) = \frac{dx(t)}{dt}$$

Ideal Differentiator

Example : Second order Analog Filter

$$y(t) = a_0 x(t) + a_1 \frac{dx}{dt} + b_1 \frac{dy}{dt} + b_2 \frac{d^2 y}{dt^2}$$

Transfer Function :

$$H(s) = \frac{\sum_{i=0}^N a_i s^i}{1 - \sum_{i=0}^M b_i s^i}$$

Example :

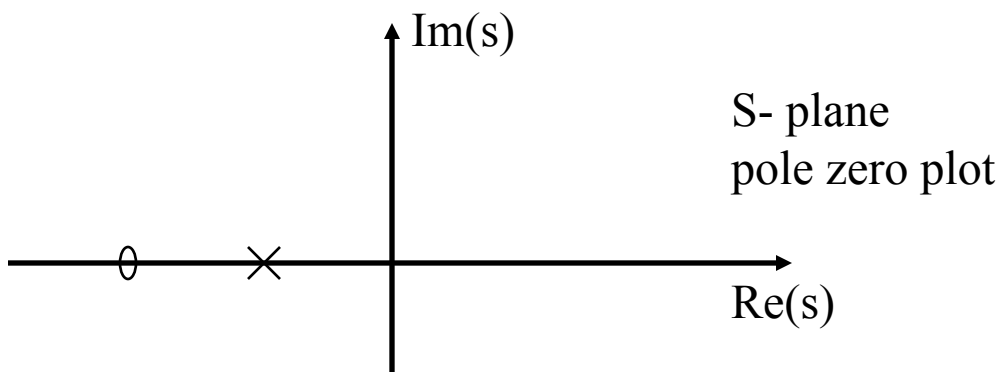
$$y(t) = x(t) + \frac{dx}{dt} - 2 \frac{dy}{dt}$$

$$H(s) = \frac{1+s}{1+2s}$$

$$H(s) = \frac{1}{2} \cdot \frac{s+1}{s+\frac{1}{2}}$$

Pole: $s = -1/2$ Zero: $s = -1$

Gain = $1/2$



Impulse Response :

$$h(t) = L^{-1} H(s)$$

Example :

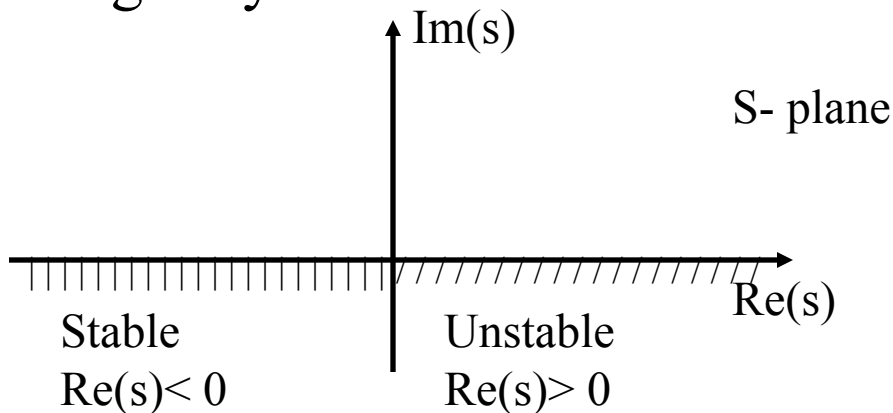
$$H(s) = \frac{a_0}{1 - b_1 s}$$

$$h(t) = \begin{cases} \frac{a_0}{b_1} e^{\frac{1}{b_1} t} & t \geq 0 \\ 0 & t < 0 \end{cases}$$

Stable Analog Filter :

Define $h(t) \rightarrow 0$ as $t \rightarrow \infty$

Implies that all poles must lie to the left of the imaginary axis :



Stability and Pole Locations :

Analog Filters with M poles:

$$H(s) = G \frac{(s - z_1)(s - z_2) \dots (s - z_N)}{(s - p_1)(s - p_2) \dots (s - p_M)}$$

Partial Fraction (no repeated poles)

$$H(s) = \frac{g_1}{s - p_1} + \frac{g_2}{s - p_2} + \dots + \frac{g_m}{s - p_m}$$

$$h(t) = g_1 e^{p_1 t} + g_2 e^{p_2 t} + \dots + g_m e^{p_m t}$$

Since stable means $h(t) \rightarrow 0$ as $t \rightarrow \infty$

It follows that : $p_i < 0$

If p_i is a complex pole :

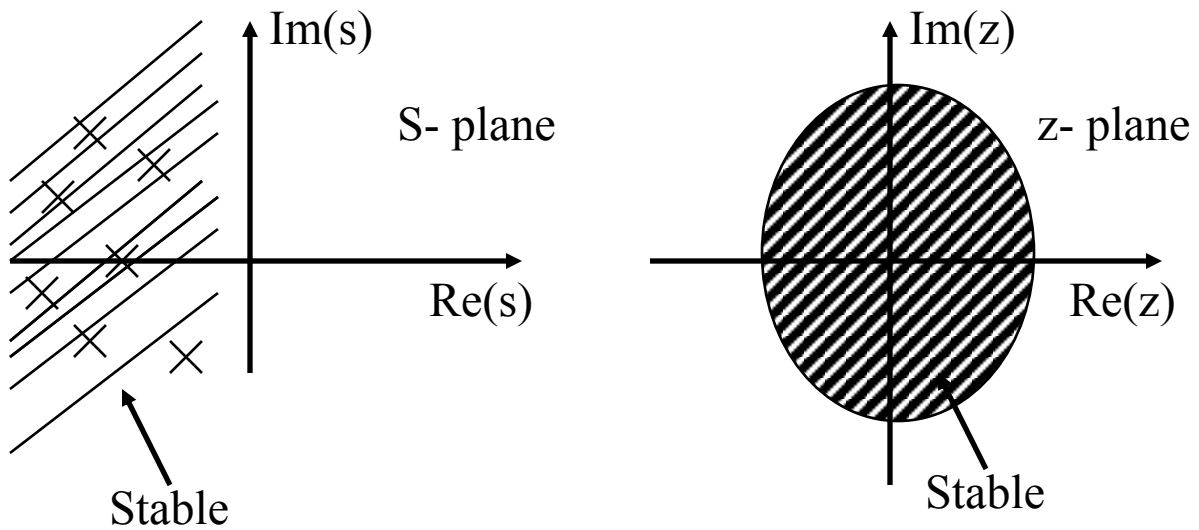
$$h_i(t) = g_i e^{\operatorname{Re}(p_i)t} e^{j\operatorname{Im}(p_i)t}$$

Follows:

$$\operatorname{Re}(p_i) < 0$$

$$|e^{j\operatorname{Im}(p_i)t}| = 1$$

Analog filters are stable when their poles are in the left half of the s-plane, whereas digital filters are stable when their poles are confined within the unit circle.



Analog Filter : Magnitude

Function :

$$H(j\omega') = H(s) \Big|_{s=j\omega'} = |H(j\omega')| < H(j\omega')$$

Magnitude Square Function :

$$|H(j\omega')|^2 = H(s)H(-s) \Big|_{s=j\omega'}$$

Example :

$$H(s) = \frac{1}{s+1}$$

$$H(-s) = \frac{1}{-s+1}$$

Follows :

$$H(s)H(-s) = \frac{1}{1-s^2}$$

$$H(s)H(-s)\Big|_{s=j\omega'} = \frac{1}{1+\omega'^2}$$

\therefore

$$|H(j\omega')|^2 = \frac{1}{1+\omega'^2}$$

$$|H(j\omega')| = \frac{1}{(1+\omega'^2)^{1/2}}$$

Example :

$$|H(j\omega')|^2 = \frac{4+\omega'^2}{1+\omega'^6}$$

Find $H(s)$ or $H(-s)$

Follows :

$$H(s)H(-s) = |H(j\omega')|^2$$

$$\omega'^2 = -s^2$$

$$= \frac{4-s^2}{1-s^6} = \frac{(2-s)(2+s)}{(1-s^3)(1+s^3)}$$

$$(1-s^3) = (1-s)(1+s+s^2)$$

$$(1+s^3) = (1+s)(1-s+s^2)$$

H(s) : poles in the left - half of the s - plane

$$H(s) = \frac{(s+2)}{(1+s)(1+s+s^2)}$$

H(-s) : poles in the right - half of the s - plane

$$H(-s) = \frac{(2-s)}{(1-s)(1-s+s^2)}$$