

# **Discrete - Time Signals and Systems**

## **Z-Transforms 2**

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## Z Transform: Review

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Given a discrete-time sequence  $x[n]$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

*$X(z)$  exists if and only if the infinite series converges*

*converging plane is called Region of convergence ROC*

$$x[n] \leftrightarrow X(z)$$

$$\delta[n] \leftrightarrow 1 \quad \text{ROC all } Z$$

$$u[n] \leftrightarrow \frac{z}{z-1} \quad \text{ROC } |z| > 1$$

$$a^n u[n] \leftrightarrow \frac{z}{z-a} \quad \text{ROC } |z| > |a|$$

$$-a^n u[-n-1] \leftrightarrow \frac{z}{z-a} \quad \text{ROC } |z| < |a|$$

$$b^{|n|} \leftrightarrow \frac{z(1-b^2)}{(1-bz)(z-b)} \quad \text{ROC } b < |z| < \frac{1}{b}$$

$$Aa^n e^{j\theta n} u[n] \leftrightarrow \frac{Az}{z-ae^{j\theta}} \quad \text{ROC } |z| > |a|$$

$$a^n u[n] - b^n u[-n-1] \leftrightarrow \frac{z}{z-a} + \frac{z}{z-b} \quad \text{ROC } \{ |z| > |a| \cap |z| < |b| \}$$

# The Inverse Z-Transform

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$$X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$
$$= \dots + x[-2]z^2 + x[-1]z^1 + x[0]z^0 + x[1]z^{-1} + \dots$$

*Inverse Z – transform is nothing but obtaining the discrete – time samples from the polynomial  $X(z)$*

*Example 1:  $X(z) = 4z^2 + 2 + 3z^{-1}$  ROC all  $z$ , except  $z = 0$  &  $\infty$*

*Compare with the definition and pick out the discrete - time samples*

$$\{x[-2], x[-1], x[0], x[1]\} = \{4, 0, 2, 3\}$$

$$\{x[-2], x[-1], x[0], x[1]\} = \{4, 0, 2, 3\}$$

$$x[n] = 0 \quad \textit{otherwise}$$

*Writing it as an equation*

$$x[n] = 4\delta[n + 2] + 2\delta[n] + 3\delta[n - 1]$$

$$\therefore \delta[n + n_0] \xleftrightarrow{z} z^{n_0}$$

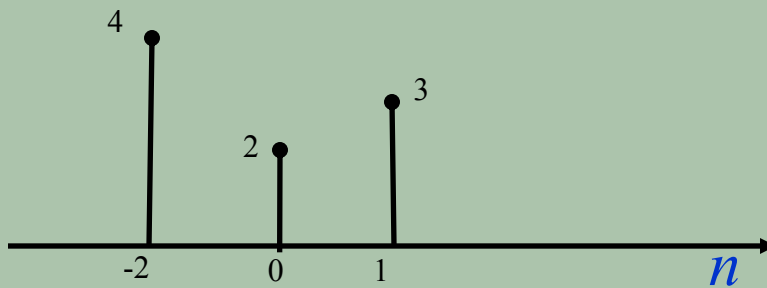


Fig.11.1

## Example 2

$$X(z) = 1 - 2z^{-1} + 3z^{-3} - z^{-5}$$

EXPONENT GIVES  
TIME LOCATION

$$x[n] = \begin{cases} 0 & n < 0 \\ 1 & n = 0 \\ -2 & n = 1 \\ 0 & n = 2 \\ 3 & n = 3 \\ 0 & n = 4 \\ -1 & n = 5 \\ 0 & n > 5 \end{cases}$$

$$x[n] = ?$$

$$x[n] = \delta[n] - 2\delta[n - 1] + 3\delta[n - 3] - \delta[n - 5]$$

## Example 3: Division method

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$$X(z) = \frac{z^2 + 1}{z^2 + z - 2}$$

*The problem can be solved through expansion, though this can be done in two ways;*

$$X(z) = \underbrace{\sum_{n=-\infty}^{-1} x[n]z^{-n}}_{\text{Left.H sequence}} + \underbrace{\sum_{n=0}^{\infty} x[n]z^{-n}}_{\text{Right.H sequence}}$$

*First consider a right handed sequence:*

$$X(z) = x[0] + x[1]z^{-1} + x[2]z^{-2} + x[3]z^{-3} + \dots$$

$$\begin{array}{r}
 z^2 + z - 2 \quad \left| \quad \frac{1 - z^{-1} + 4z^{-2} - 6z^{-3} + \dots}{z^2 + 1} \right. \\
 \underline{z^2 + z - 2} \\
 -z + 3 \\
 \underline{-z - 1 + 2z^{-1}} \\
 4 - 2z^{-1} \\
 \underline{4 + 4z^{-1} - 8z^{-2}} \\
 -6z^{-1} + 8z^{-2}
 \end{array}$$

$$\therefore X(z) = 1 - z^{-1} + 4z^{-2} - 6z^{-3} + \dots$$

*By inspection,*

$$\{x[0], x[1], x[2], x[3], \dots\} = \{1, -1, 4, -6, \dots\}$$



Now consider a left handed sequence :

$$X(z) = \dots + x[-3]z^3 + x[-2]z^2 + x[-1]z^1$$

$$\begin{array}{r} -2 + z + z^2 \\ \hline \end{array} \begin{array}{r} -\left(\frac{1}{2}\right) - \left(\frac{1}{4}\right)z - \left(\frac{7}{8}\right)z^2 + \dots \\ \hline 1 + 0z + z^2 \\ \hline 1 - \left(\frac{1}{2}\right)z - \left(\frac{1}{2}\right)z^2 \\ \hline \left(\frac{1}{2}\right)z + \left(\frac{3}{2}\right)z^2 \\ \hline \left(\frac{1}{2}\right)z - \left(\frac{1}{4}\right)z^2 - \left(\frac{1}{4}\right)z^3 \\ \hline \left(\frac{7}{4}\right)z^2 + \left(\frac{1}{4}\right)z^3 \end{array}$$

$$\therefore X(z) = -\frac{1}{2} - \left(\frac{1}{4}\right)z - \left(\frac{7}{8}\right)z^2 + \dots$$

By inspection,

$$\{\dots, x[-2], x[-1]\} = \{\dots, -\left(\frac{7}{8}\right), -\left(\frac{1}{4}\right)\}$$

*Example 4*:  $X(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - z^{-1} + 0.3561z^{-2}}$ , find Right.h sequence  $x[n]$ ?

$$\begin{array}{r}
 \underline{1 + 3z^{-1} + 3.6439z^{-2} + 2.5756z^{-3} + \dots} \\
 1 - z^{-1} + 0.3561z^{-2} \quad 1 + 2z^{-1} + z^{-2} \\
 \underline{1 - z^{-1} + 0.3561z^{-2}} \\
 \quad 3z^{-1} + 0.6439z^{-2} \\
 \quad \underline{3z^{-1} - 3z^{-2} + 1.0683z^{-3}} \\
 \qquad 3.6439z^{-2} - 1.0683z^{-3} \\
 \qquad \underline{3.6439z^{-2} - 3.6439z^{-3} + 1.297z^{-4}} \\
 \qquad \qquad 2.575z^{-3} - 1.297z^{-4}
 \end{array}$$

$\therefore X(z) = 1 + 3z^{-1} + 3.6439z^{-2} + 2.5756z^{-3} + \dots$

*By inspection*,  $\{x[0], x[1], x[2], x[3], \dots\} = \{1, 3, 3.6439, 2.5756, \dots\}$

## Example 5: Partial Fraction Method

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$$X(z) = \frac{z^2}{(z - 1/2)(z - 1/3)}$$

$$= \frac{c_1 z}{(z - 1/2)} + \frac{c_2 z}{(z - 1/3)}$$

$$c_1 = X(z) \frac{(z - 1/2)}{z} \Big|_{z=1/2} = \frac{z}{(z - 1/3)} \Big|_{z=1/2} = 3$$

$$c_2 = X(z) \frac{(z - 1/3)}{z} \Big|_{z=1/3} = \frac{z}{(z - 1/2)} \Big|_{z=1/3} = -2$$

$$X(z) = \frac{3z}{(z - 1/2)} - \frac{2z}{(z - 1/3)}$$

### *Continued Example 5*

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$$X(z) = \frac{3z}{(z - 1/2)} - \frac{2z}{(z - 1/3)}$$

*Depending on ROC multiple results are possible*

*if ROC is  $|z| > 1/2$*

$$x[n] = 3(1/2)^n u[n] - 2(1/3)^n u[n]$$

*if ROC is  $|z| < 1/3$*

$$x[n] = -3(1/2)^n u[-n - 1] + 2(1/3)^n u[-n - 1]$$

*if ROC is  $1/2 < |z| < 1/3$*

$$x[n] = 3(1/2)^n u[n] + 2(1/3)^n u[-n - 1]$$

## Example 6: Partial Fraction Method

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$$X(z) = \frac{z^{-1}}{1 - 0.25z^{-1} - 0.375z^{-2}}$$

*Multiplying the numerator and denominator by  $z^2$ ,*

$$X(z) = \frac{z}{z^2 - 0.25z - 0.375} = \frac{z}{(z - 0.75)(z + 0.5)}$$

$$\begin{aligned} X(z) &= \frac{z}{(z - 0.75)(z + 0.5)} \\ &= \frac{C_1 z}{z - 0.75} + \frac{C_2 z}{z + 0.5} \end{aligned}$$

$$\begin{aligned} C_1 &= \frac{X(z)}{z} (z - 0.75) \Big|_{z=0.75} = \frac{(z - 0.75)}{(z - 0.75)(z + 0.5)} \Big|_{z=0.75} \\ &= \frac{1}{z + 0.5} \Big|_{z=0.75} = \frac{4}{5} \end{aligned}$$

### Continued Example 6

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$$C_2 = \frac{X(z)}{z} (z + 0.5) \Big|_{z=-0.5} = \frac{1}{z - 0.75} \Big|_{z=-0.5} = -\frac{4}{5}$$

$$\therefore X(z) = \frac{(4/5)z}{z-0.75} - \frac{(4/5)z}{z+0.5} = (4/5) \left[ \frac{z}{z-0.75} - \frac{z}{z+0.5} \right]$$

if ROC is  $|z| > 0.75$

$$x[n] = (4/5) \left( (0.75)^n u[n] - (-0.5)^n u[n] \right)$$

if ROC is  $|z| < 0.5$

$$x[n] = (4/5) \left( -(0.75)^n u[-n-1] + (-0.5)^n u[-n-1] \right)$$

if ROC is  $0.5 < |z| < 0.75$

$$x(n) = (4/5) \left( (0.75)^n u[n] + (-0.5)^n u[-n-1] \right)$$

## Example 7: Partial Fraction Method

$$X(z) = \frac{b_0 + b_1 z^{-1}}{(1 - a_1 z^{-1})(1 - z^{-1})}, \quad \text{ROC } |z| > a_1 > 1$$

$$X(z) = \frac{A}{(1 - a_1 z^{-1})} + \frac{B}{(1 - z^{-1})}$$

$$A = X(z)(1 - a_1 z^{-1}) \Big|_{z=a_1} = \frac{b_0 + b_1 z^{-1}}{(1 - z^{-1})} \Big|_{z=a_1}$$

$$= \frac{b_0 + b_1 a_1^{-1}}{(1 - a_1^{-1})}$$

$$B = X(z)(1 - z^{-1}) \Big|_{z=1} = \frac{b_0 + b_1 z^{-1}}{(1 - a_1 z^{-1})} \Big|_{z=1}$$

$$= \frac{b_0 + b_1}{(1 - a_1)}$$

### Continued Example 7

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$$X(z) = \frac{b_0 + b_1 z^{-1}}{(1 - a_1 z^{-1})(1 - z^{-1})}, \quad \text{ROC } |z| > a_1 > 1$$

$$X(z) = \frac{b_0 + b_1 a_1^{-1}}{(1 - a_1^{-1})} \frac{1}{(1 - a_1 z^{-1})} + \frac{b_0 + b_1}{(1 - a_1)} \frac{1}{(1 - z^{-1})}$$

$$x[n] = \frac{b_0 + b_1 a_1^{-1}}{(1 - a_1^{-1})} a_1^n u[n] + \frac{b_0 + b_1}{(1 - a_1)} u[n]$$

$$x[n] = \left\{ \frac{b_0 + b_1 a_1^{-1}}{(1 - a_1^{-1})} a_1^n + \frac{b_0 + b_1}{(1 - a_1)} \right\} u[n]$$

*Always try to resolve the given equation into library functions so that it is easy to obtain the inverse Z – transform*



## Example 8: Partial Fraction Method

$$X(z) = \frac{1 - 2.1z^{-1}}{1 - 0.3z^{-1} - 0.4z^{-2}}, \quad \text{ROC } |z| > 0.8$$

$$X(z) = \frac{1 - 2.1z^{-1}}{(1 + 0.5z^{-1})(1 - 0.8z^{-1})} = \frac{A}{(1 + 0.5z^{-1})} + \frac{B}{(1 - 0.8z^{-1})}$$

$$A = X(z)(1 + 0.5z^{-1}) \Big|_{z=-0.5} = \frac{1 - 2.1z^{-1}}{(1 - 0.8z^{-1})} \Big|_{z=-0.5} = \frac{1 + 4.2}{1 + 1.6} = 2$$

$$B = X(z)(1 - 0.8z^{-1}) \Big|_{z=0.8} = \frac{1 - 2.1z^{-1}}{(1 + 0.5z^{-1})} \Big|_{z=0.8} = \frac{1 - 2.1/0.8}{(1 + 0.5/0.8)} = -1$$

$$X(z) = \frac{2}{(1 + 0.5z^{-1})} - \frac{1}{(1 - 0.8z^{-1})}$$

$$x[n] = \left( -(-0.5)^n + (0.8)^n \right) u[n]$$

# Z Transform: Properties

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## Superposition

Since the Z – transform is linear

$$ax_1[n] + bx_2[n] \xleftrightarrow{z} aX_1(z) + bX_2(z)$$

## Shifting

$$x[n - n_0] \xleftrightarrow{z} z^{-n_0} X(z)$$

$$\therefore x[n - 1] \xleftrightarrow{z} z^{-1} X(z)$$

$$x[n + 1] \xleftrightarrow{z} z^1 X(z)$$

$$x[n + 2] \xleftrightarrow{z} z^2 X(z)$$

$$x[n - 2] \xleftrightarrow{z} z^{-2} X(z)$$

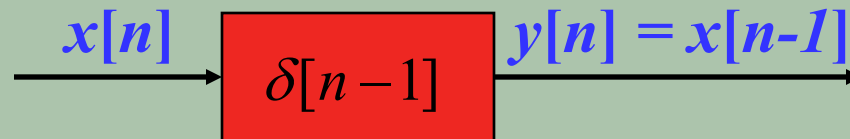
# Unit Delay

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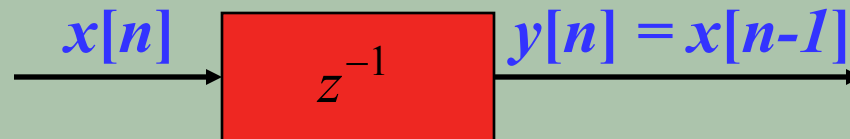
## Symbolic Notation



## Mathematical Notation



$$\because \delta[n-1] \xleftrightarrow{z} z^{-1}$$



# Example 1

Consider the first difference of two successive signal values

$$y[n] = x[n] - x[n - 1]$$

Apply the Z-transform on both sides

$$Z\{y[n]\} = Z\{x[n] - x[n - 1]\}$$

$$\Rightarrow Y(z) = X(z) - Z^{-1}X(z)$$

$$Y(z) = X(z)(1 - Z^{-1})$$

**Computational structure for the above system**

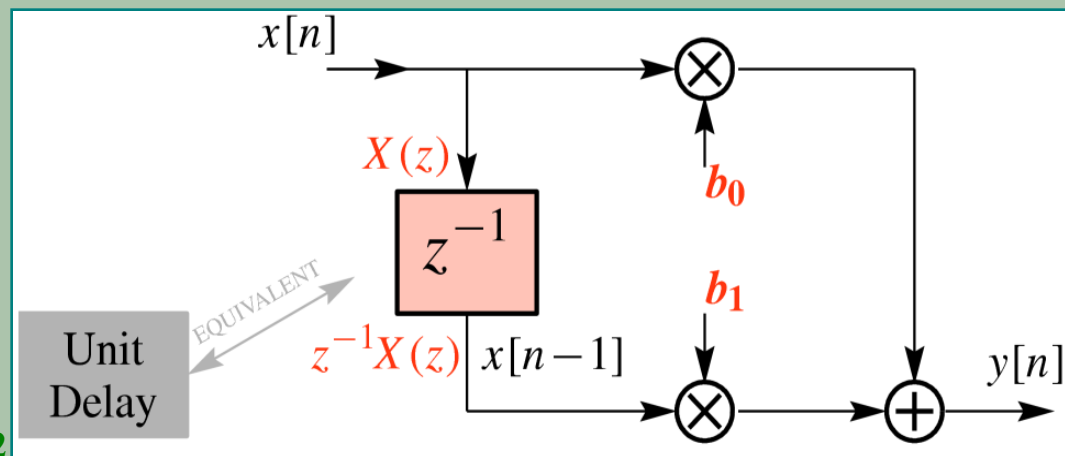


Fig.11.2

## Example 2

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$$y[n] = \frac{1}{2} y[n-1] + x[n]$$

*Apply the Z – transform on both sides*

$$Z \{ y[n] \} = Z \left\{ \frac{1}{2} y[n-1] + x[n] \right\}$$

$$\Rightarrow Y(z) = \frac{1}{2} Z^{-1} Y(z) + X(z)$$

$$Y(z) - \frac{1}{2} Z^{-1} Y(z) = X(z)$$

$$Y(z) \left( 1 - \frac{1}{2} Z^{-1} \right) = X(z)$$

$$Y(z) = \frac{X(z)}{\left( 1 - \frac{1}{2} Z^{-1} \right)}$$

## Continued Example 2

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$$y[n] = \frac{1}{2} y[n-1] + x[n]$$

$$Y(z) = \frac{X(z)}{\left(1 - \frac{1}{2} Z^{-1}\right)}$$

Let the input be  $x[n] = \delta[n]$ ,

the output will be the impulse response  $y[n] = h[n]$

$$\because \delta[n] \xleftrightarrow{z} 1, X(z) = 1$$

$$Y(z) = H(z)$$

$$H(z) = \frac{1}{\left(1 - \frac{1}{2} Z^{-1}\right)}$$

$$h[n] = \mathcal{Z}^{-1} [H(z)]$$

## *Continued Example 2*

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$$H(z) = \frac{1}{(1 - \frac{1}{2} Z^{-1})}$$

$$\text{With ROC } |z| > \frac{1}{2}$$

$$h[n] = (1/2)^n u[n]$$

$$\text{With ROC } |z| < \frac{1}{2}$$

$$h[n] = -(1/2)^n u[-n-1]$$

*A standard notation for Transfer function*

$$H(z) = \frac{Y(z)}{X(z)}$$

## Example 3

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*Find the transfer function for the system described by*

$$y[n] = -\frac{1}{2}y[n-1] + x[n] + x[n-1]$$

*Apply the Z – transform on both sides*

$$Z\{y[n]\} = Z\left\{-\frac{1}{2}y[n-1] + x[n] + x[n-1]\right\}$$

$$\Rightarrow Y(z) = -\frac{1}{2}Z^{-1}Y(z) + X(z) + z^{-1}X(z)$$

$$Y(z)\left(1 + \frac{1}{2}Z^{-1}\right) = X(z)(1 + z^{-1})$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{(1 + z^{-1})}{\left(1 - \frac{1}{2}Z^{-1}\right)}$$



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## Reference

James H. McClellan, Ronald W. Schafer and Mark A. Yoder, “7.1-7.4, 8.7--Signal Processing First”, Prentice Hall, 2003

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