

# **Discrete - Time Signals and Systems**

## **IIR Filters Introduction**

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## General form of *Difference equations*

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$$y[n] = \sum_{l=1}^N a_l y[n-l] + \sum_{k=0}^M b_k x[n-k]$$

*Recursive equation; Represents IIR filters*

$a_l$  ... *feedback* coefficients

$b_k$  ... *feed - forward* coefficients

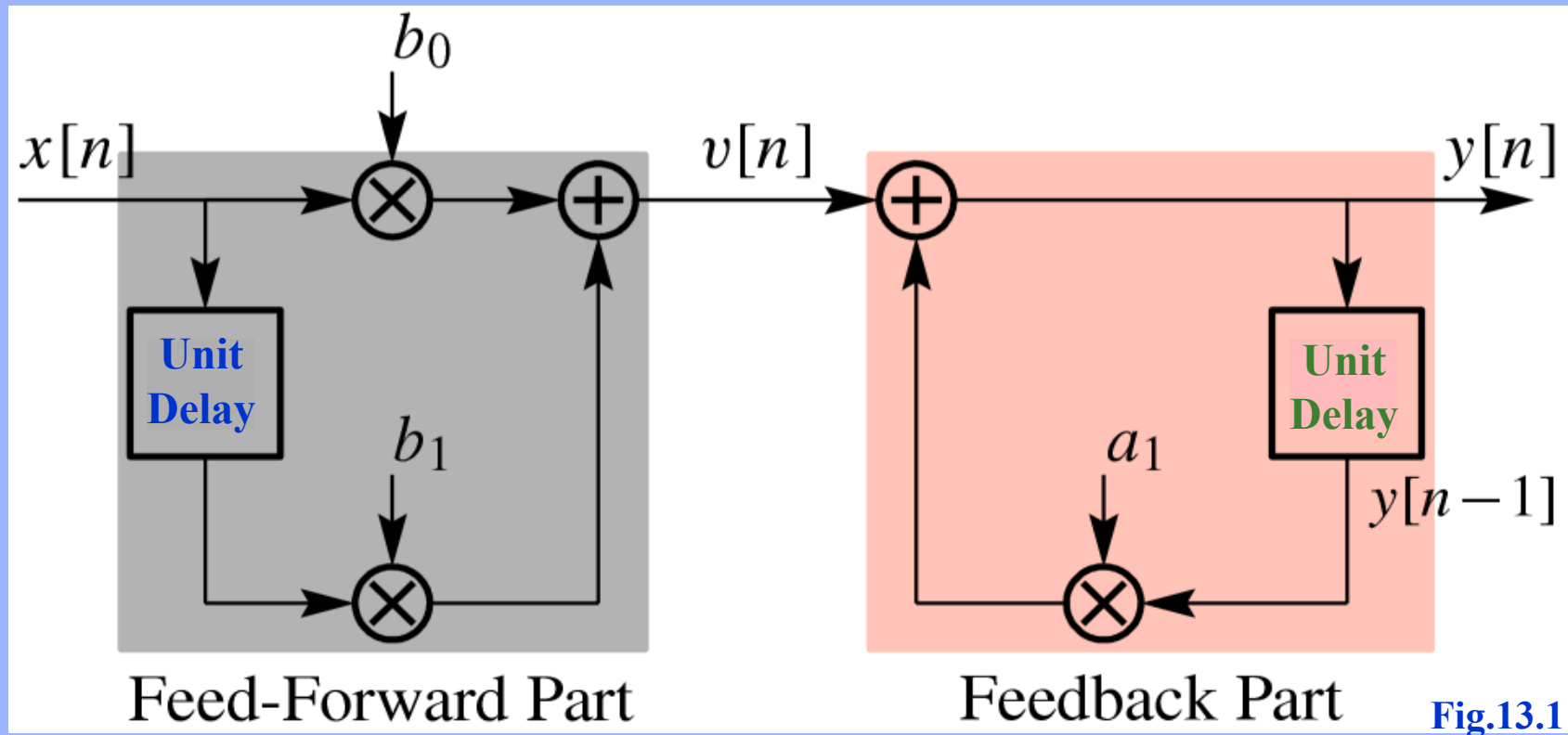
$N + M + 1$  ... *Total coefficients*

$N$  ... *Order of IIR filters*

## IIR: Block Diagram Representation

Consider a first – order general equation

$$y[n] = a_1 y[n - 1] + b_0 x[n] + b_1 x[n - 1]$$



## *Example: IIR Filter*

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$$y[n] = a_1 y[n-1] + b_0 x[n] + b_1 x[n-1]$$

$$\text{Let, } a_1 = 0.8$$

$$b_0 = 5$$

$$y[n] = 0.8 y[n-1] + 5x[n]$$

*Initial rest conditions :*

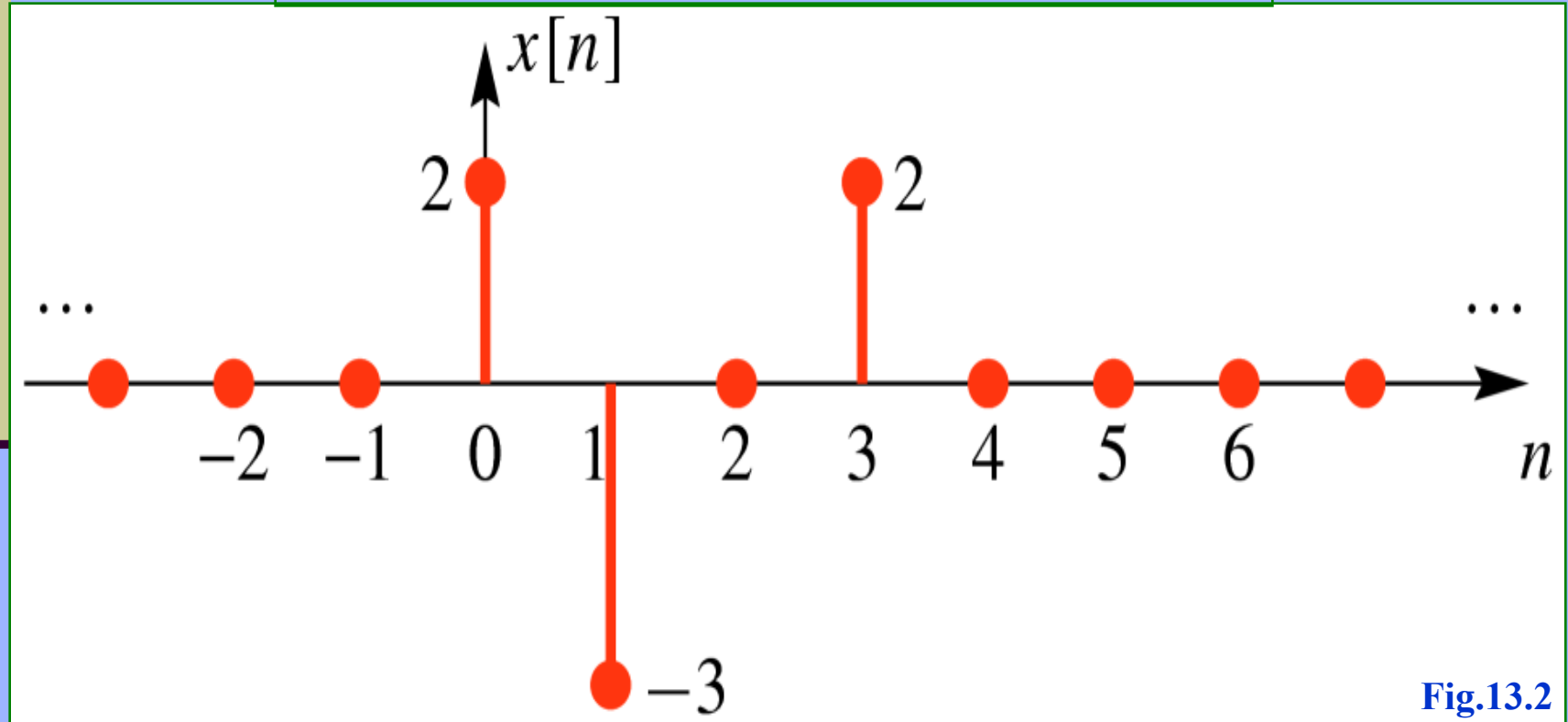
$$x[n] = 0 \quad \text{for } n < 0$$

$$y[n] = 0 \quad \text{for } n < 0$$

*Input*

$$x[n] = 2\delta[n] - 3\delta[n-1] + 2\delta[n-3]$$

*Total of 4 samples*



**Fig.13.2**

$$y[0] = 0.8y[-1] + 5x[0]$$

$y[-1] = 0 \dots$  *initial rest conditions*

$$y[0] = 5x[0] = 5 \cdot 2 = 10$$

*Continue the recursion;*

$$y[1] = 0.8y[0] + 5x[1] = 0.8(10) + 5(-3) = -7$$

$$y[2] = 0.8y[1] + 5x[2] = 0.8(-7) + 5(0) = -5.6$$

$$y[3] = 0.8y[2] + 5x[3] = 0.8(-5.6) + 5(2) = 5.52$$

$$y[4] = 0.8y[3] + 5x[4] = 0.8(5.52) + 5(0) = 4.416$$

$$y[5] = 0.8y[4] + 5x[5] = 0.8(4.416) + 5(0) = 3.5328$$

$$y[6] = 0.8y[5] + 5x[6] = 0.8(3.5328) + 5(0) = 2.8262$$

$$\because x[n] = 0 \quad \text{for } n > 3$$

$$y[n] = 0.8y[n-1] \quad \text{for } n > 3$$

$$y[n] = y[3](0.8)^{n-3} \quad \text{for } n \geq 3$$

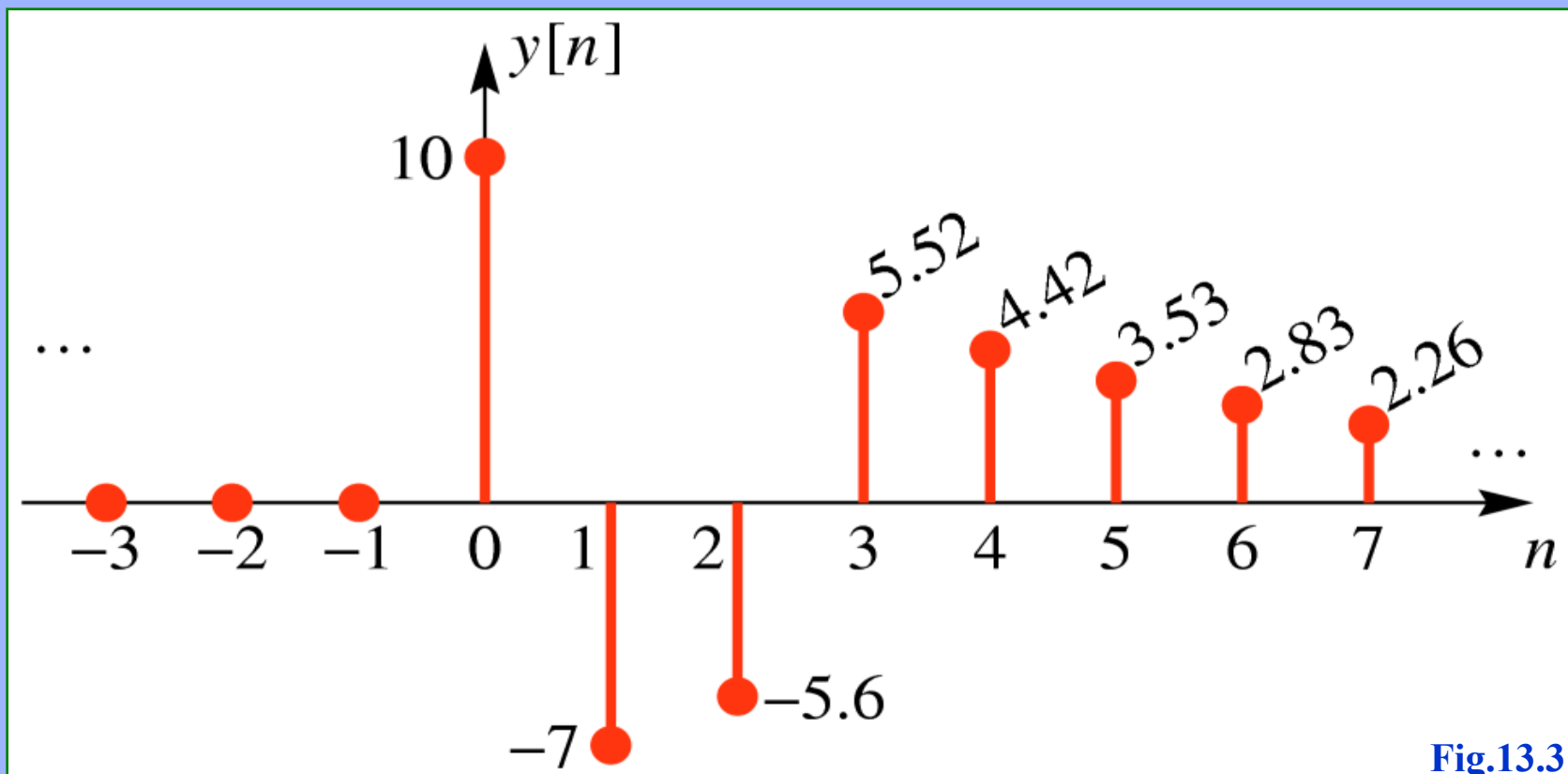


Fig.13.3

## *Impulse response of first order IIR system*

$$y[n] = a_1 y[n-1] + b_0 x[n]$$

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*Solution :*

$$n = 1 \quad y[1] = a_1 y[0] + b_0 x[1]$$

$$n = 2 \quad y[2] = a_1 y[1] + b_0 x[2]$$

$$= a_1 (a_1 y[0] + b_0 x[1]) + b_0 x[2]$$

$$= a_1^2 y[0] + a_1 b_0 x[1] + b_0 x[2]$$

$$n = 3 \quad y[3] = a_1 y[2] + b_0 x[3]$$



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$$= a_1 \left( a_1^2 y[0] + a_1 b_0 x[1] + b_0 x[2] \right) + b_0 x[3]$$

$$y[3] = a_1^3 y[0] + a_1^2 b_0 x[1] + a_1 b_0 x[2] + b_0 x[3]$$

*Generalizing the 1<sup>st</sup> order discrete-time system,*

$$y[n] = a_1^n y[0] + b_0 \left[ a_1^{n-1} x[1] + a_1^{n-2} x[2] + \dots + a_1^0 x[n] \right]$$

$$y[n] = a_1^n y[0] + b_0 \sum_{m=1}^n a_1^{(n-m)} x[m]$$

If  $x[n] = \delta[n]$  then  $y[n] = h[n]$

$$y[n] = a_1 y[n-1] + b_0 x[n]$$

$$h[n] = a_1 y[n-1] + b_0 \delta[n]$$

$$y[n] = a_1^n y[0] + b_0 \sum_{m=1}^n a_1^{(n-m)} x[m]$$

$$\because y[0] = a_1 y[-1] + b_0 x[0] = a_1 \cdot 0 + b_0 \cdot 1 = b_0$$

$$h[n] = b_0 a_1^n + b_0 \sum_{m=1}^n a_1^{(n-m)} 0$$

$$h[n] = \begin{cases} b_0 a_1^n & \text{for } n \geq 0 \\ 0 & \text{for } n < 0 \end{cases}$$

## Tabular form: Impulse Response

$$h[n] = a_1 h[n-1] + b_0 \delta[n]$$

$n$	$n < 0$	0	1	2	3	4
$\delta[n]$	0	1	0	0	0	0
$h[n-1]$	0	0	$b_0$	$b_0(a_1)$	$b_0(a_1)^2$	$b_0(a_1)^3$
$h[n]$	0	$b_0$	$b_0(a_1)$	$b_0(a_1)^2$	$b_0(a_1)^3$	$b_0(a_1)^4$

From this table it is obvious that the general formula is

$$h[n] = \begin{cases} b_0(a_1)^n & \text{for } n \geq 0 \\ 0 & \text{for } n < 0 \end{cases}$$

$$\begin{aligned} h[n] &= b_0(a_1)^n u[n] \\ u[n] &= 1, \quad \text{for } n \geq 0 \end{aligned}$$



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*Impulse response of a more general 1<sup>st</sup> order IIR system*

$$y[n] = a_1 y[n-1] + b_0 x[n] + b_1 x[n-1]$$

$$h[n] = a_1 h[n-1] + b_0 \delta[n] + b_1 \delta[n-1]$$

*Using the principle of superposition and previous result;*

$$h[n] = b_0 (a_1)^n u[n] \text{ for the system}$$

$$y[n] = a_1 y[n-1] + b_0 x[n]$$

*For the present system*

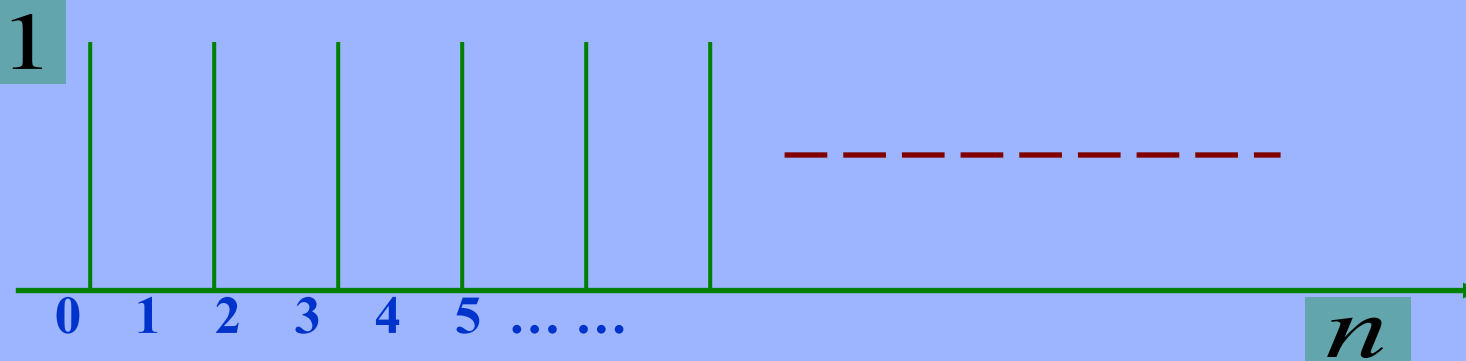
$$h[n] = b_0 a_1^n u[n] + b_1 a_1^{n-1} u[n-1]$$

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## Unit Step Sequence Input

$$y[n] = a_1 y[n-1] + b_0 x[n]$$

Let  $x[n] = u[n] = 1$  for all  $n, n \geq 0$



$$y[n] = a_1^n y[0] + b_0 \left[ a_1^{n-1} x[1] + a_1^{n-2} x[2] + \dots + a_1^0 x[n] \right]$$

$$y[0] = a_1 y[-1] + b_0 x[0] = a_1 \cdot 0 + b_0 \cdot 1 = b_0$$

$$y[n] = a_1 y[n - 1] + b_0 x[n]$$

$n$	$x[n]$	$y[n]$
$n < 0$	0	0
0	1	$b_0$
1	1	$b_0 + b_0(a_1)$
2	1	$b_0 + b_0(a_1) + b_0(a_1)^2$
3	1	$b_0(1 + a_1 + a_1^2 + a_1^3)$
4	1	$b_0(1 + a_1 + a_1^2 + a_1^3 + a_1^4)$
$\vdots$	1	$\vdots$

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$$y[n] = a_1^n b_0 + b_0 \left[ a_1^{n-1} x[1] + a_1^{n-2} x[2] + \dots + a_1^0 x[n] \right]$$
$$= b_0 \left[ a_1^n + a_1^{n-1} + a_1^{n-2} + \dots + 1 \right]$$

$$y[n] = b_0 \left( \frac{1 - a_1^{n+1}}{1 - a_1} \right) \quad a_1 \neq 1$$

if  $a_1 > 1$   $a_1^{n+1}$  will dominate the denominator

$$\lim_{n \rightarrow \infty} a_1^{n+1} \rightarrow \infty$$

$y[n]$ ... Will be *unstable*



if  $a_1 < 1$  then  $\lim_{n \rightarrow \infty} a_1^{n+1} \rightarrow 0$ ;

$y[n]$ ... Will be *stable*;  $y[n] = \frac{b_0}{1 - a_1}$

if  $a_1 = 1$ ;  $y[n] = \frac{0}{0}$ , unbounded output

$$\begin{aligned} \lim_{a_1 \rightarrow 1} b_0 \left( \frac{1 - a_1^{n+1}}{1 - a_1} \right) &= b_0 \lim_{a_1 \rightarrow 1} \frac{\frac{d}{da_1} (1 - a_1^{n+1})}{\frac{d}{da_1} (1 - a_1)} \\ &= b_0 \lim_{a_1 \rightarrow 1} \frac{(n+1)a_1^n}{1} = b_0 (n+1)1^n = b_0 (n+1) \end{aligned}$$

## Example: Unit Step Response

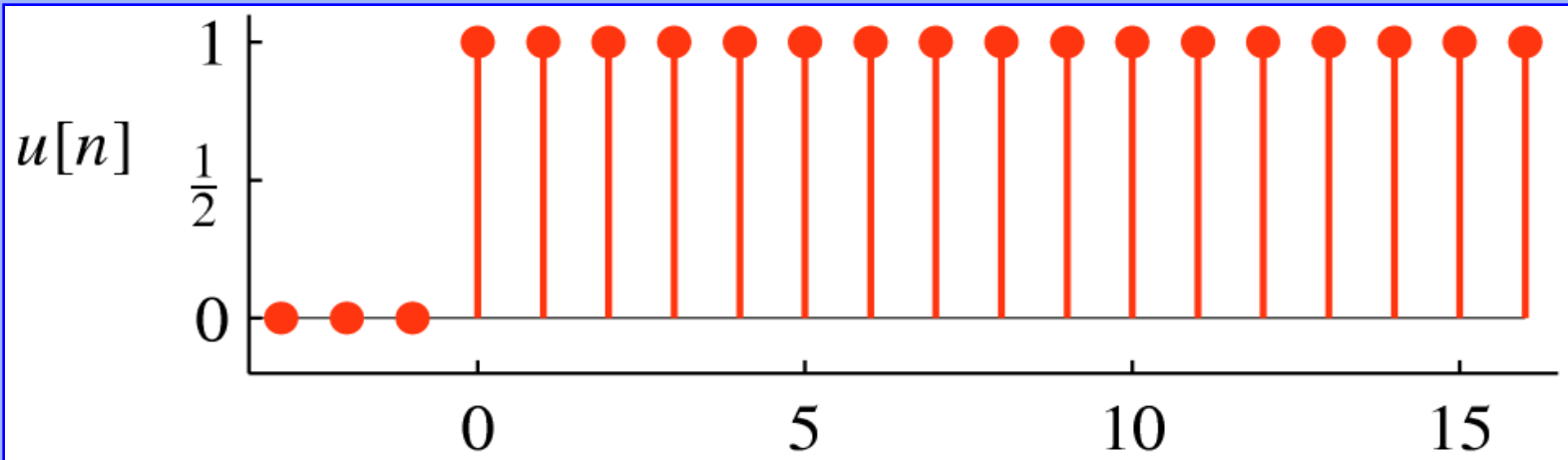
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$$y[n] = 0.8y[n-1] + 3x[n]$$

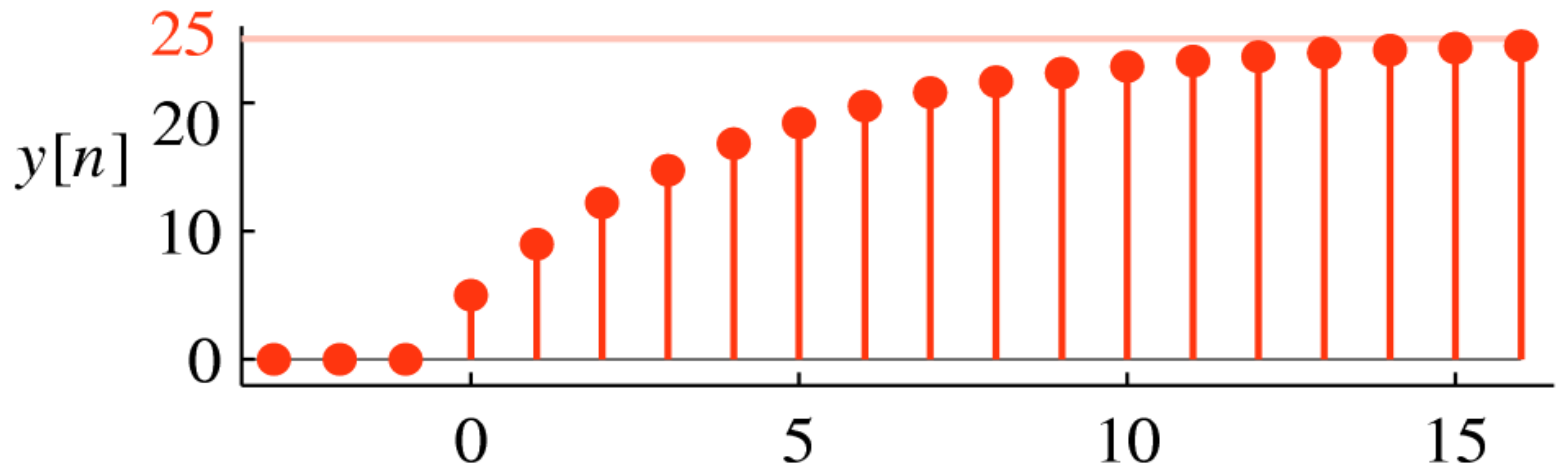
$$a_1 = 0.8$$

$$b_0 = 3$$

$$\begin{aligned} y[n] &= b_0 \left( \frac{1 - a_1^{n+1}}{1 - a_1} \right) \quad a_1 \neq 1 \\ &= 3 \left( \frac{1 - 0.8^{n+1}}{1 - 0.8} \right) = 3 \left( \frac{1 - 0.8^{n+1}}{0.2} \right) \\ &= 15 \left( 1 - 0.8^{n+1} \right) \end{aligned}$$



(a)



Time Index ( $n$ )

(b)

$$y[n] = 15(1 - 0.8^{n+1})u[n]$$

Fig.13.5

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## Reference

James H. McClellan, Ronald W. Schafer  
and Mark A. Yoder, “ 8.1 and 8.2  
“Signal Processing First”, Prentice  
Hall, 2003

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