

# ECE 122A VLSI Principles Lecture 14

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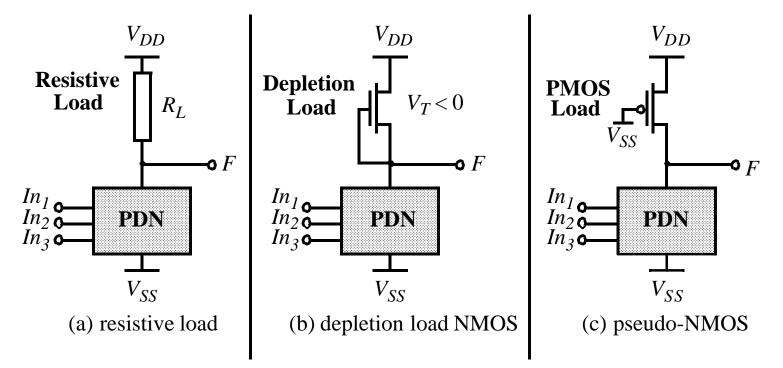
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#### **Ratioed Logic**

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#### **Ratioed Logic**

#### Need N+1 transistors vs 2N for complementary CMOS



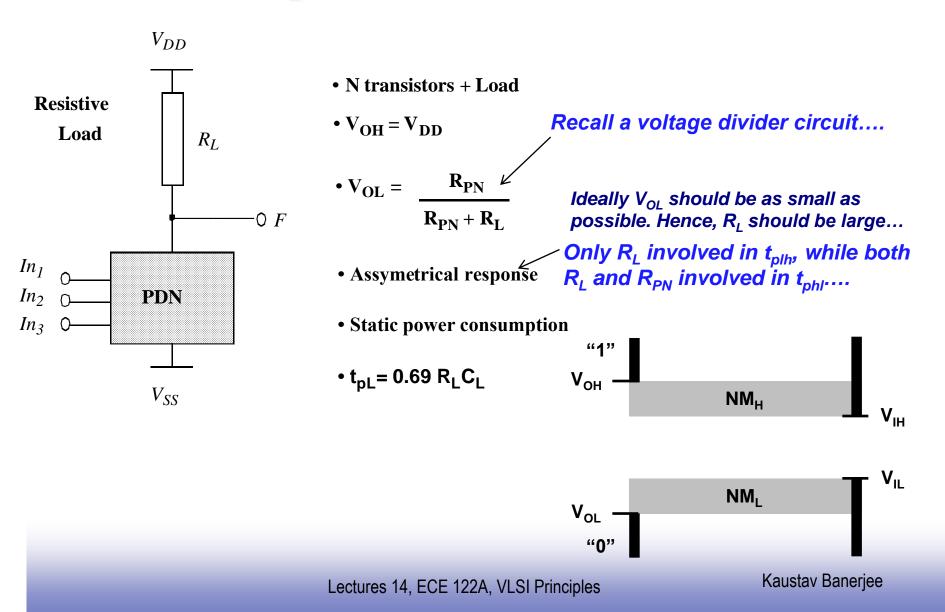
Note: a depletion mode NMOS is normally ON...an n-type channel connects the source and drain and a negative gate bias is needed to turn it off.....

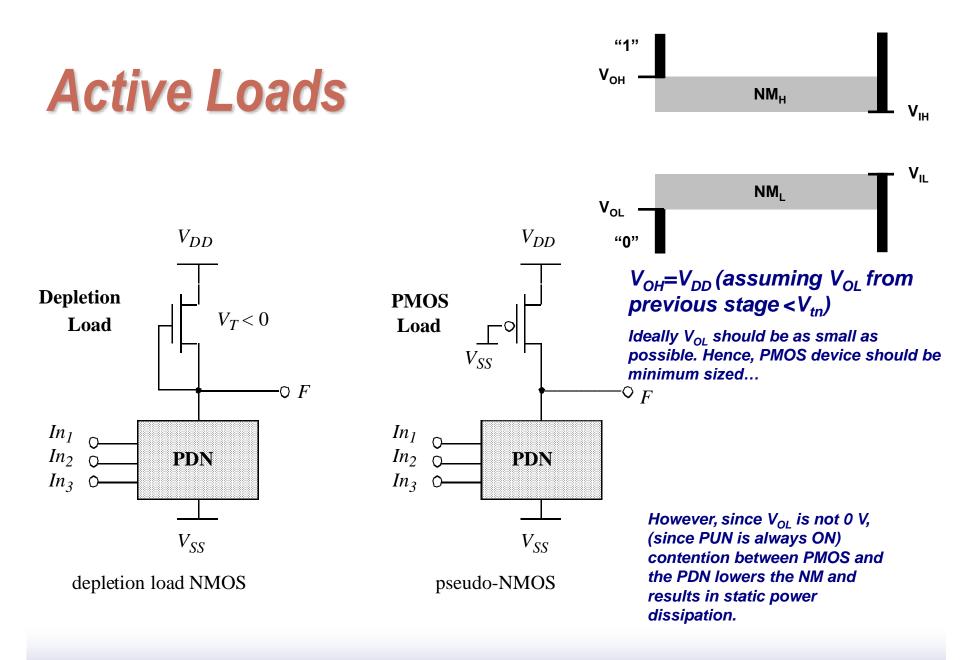
**Goal: to reduce the number of devices over complementary CMOS** 

....and gets rid of (almost) the PMOS devices....

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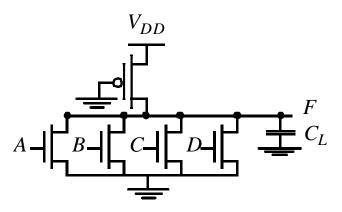
#### **Ratioed Logic: Resistive Load**





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#### **Pseudo-NMOS**



$$V_{OH} = V_{DD}$$
 (similar to complementary CMOS)

To Find  $V_{OL}$ :

$$k_{n}\left((V_{DD} - V_{Tn})V_{OL} - \frac{V_{OL}^{2}}{2}\right) + k_{p}\left((-V_{DD} - V_{Tp})V_{DSATp} - V_{DSATp}^{2}/2\right) = 0$$

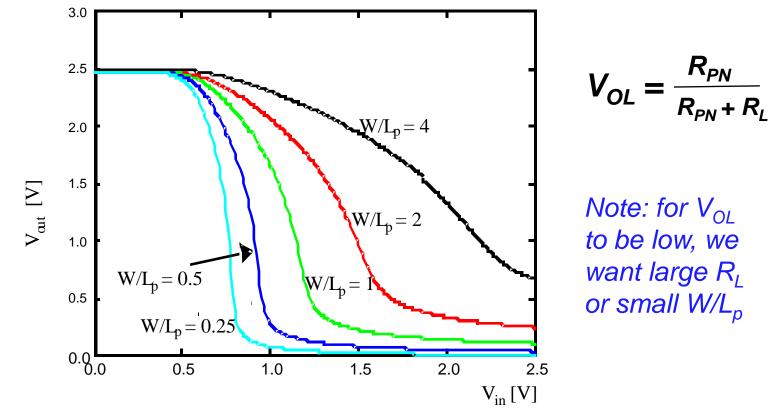
Note: NMOS in linear mode, since ideally the output=0 V ( $V_{ds}=V_{OL} < V_{qs}-V_{tn}$ ) Note: PMOS in saturation mode

 $V_{OL} = \mu_p / \mu_n W_p / W_n V_{DSATp}$ Assuming  $V_{OL}$  is small relative to gate drive,  $(V_{DD} - V_T)$ , and  $V_{Tp} = V_{Tn}$ SMALLER AREA & LOAD <u>BUT</u> STATIC POWER DISSIPATION!!!

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#### **Pseudo-NMOS VTC**

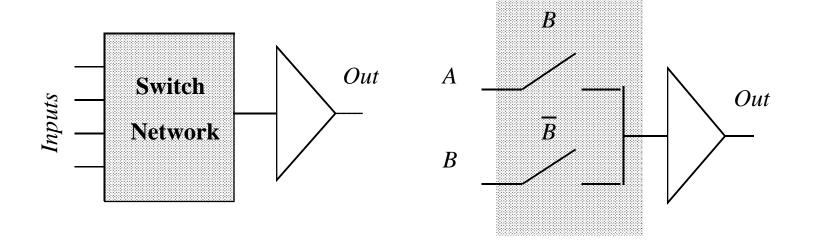
Sizing of the load device can be used to trade off parameters such as NM, delay, and power.....



A larger pull-up device (smaller  $R_L$ ) improves performance but increases static power and degrades NM by increasing  $V_{OL}$ 

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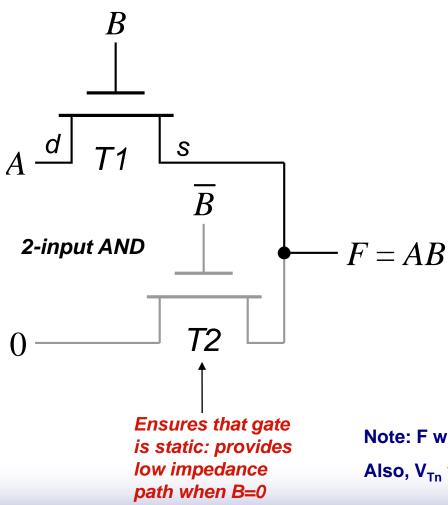
#### **Pass-Transistor Logic**



- N transistors
- No static consumption

Allows primary inputs to drive gate terminals as well as source-drain terminals

#### **Example: AND Gate**



*If B=1 then T1 is ON and T2 is OFF Then A=F*, *i.e., if A=1, F=1 and if A=0, F=0* 

When B=0, T2 is ON and passes a Zero

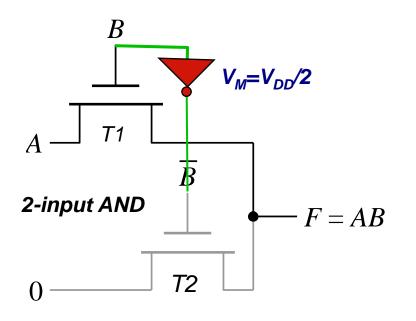
**Need fewer transistors**: 4 to implement the AND: lower cap.

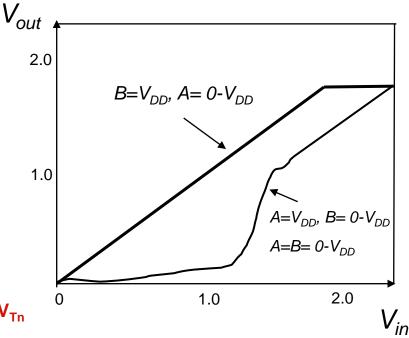
Need 6 to implement in static CMOS (4 for NAND and 2 for INV)

Note: F will charge only up to  $V_{DD}$ -  $V_{tn}$ Also,  $V_{Tn}$  will be a function of  $V_F$  (increase due to RBB)

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#### VTC of Pass-Transistor AND Gate





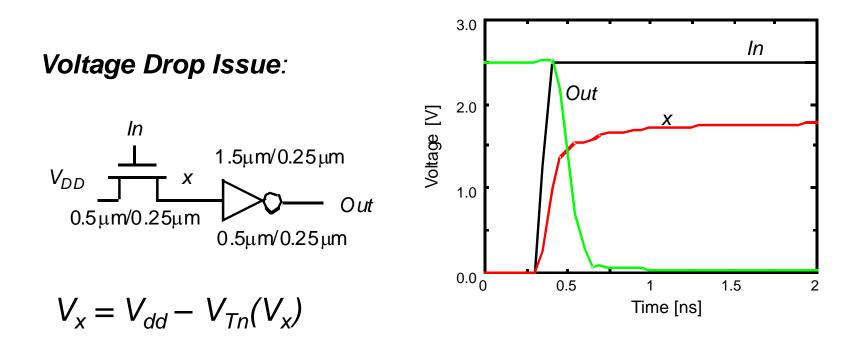
When  $B=V_{DD}$ , T1 is ON until the input reaches  $V_{DD}-V_{Tn}$ 

When  $A=V_{DD}$ , and B makes a transition from 0 to 1, T2 is turned on until  $V_{DD}/2$  and Output =0. Once T2 is turned off, output follows the input B minus a threshold drop.

VTC of Pass Transistor Logic is data dependent

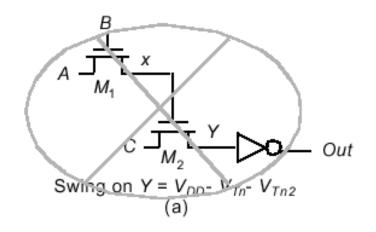
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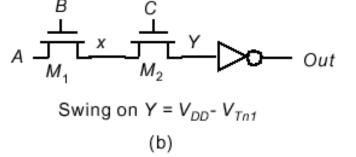
### **NMOS-Only Logic**



Hence, pass transistor gates cannot be cascaded by connecting the output of a pass gate to the gate input of another pass transistor. They can only be cascaded in series....

#### **Cascading Pass Transistors**



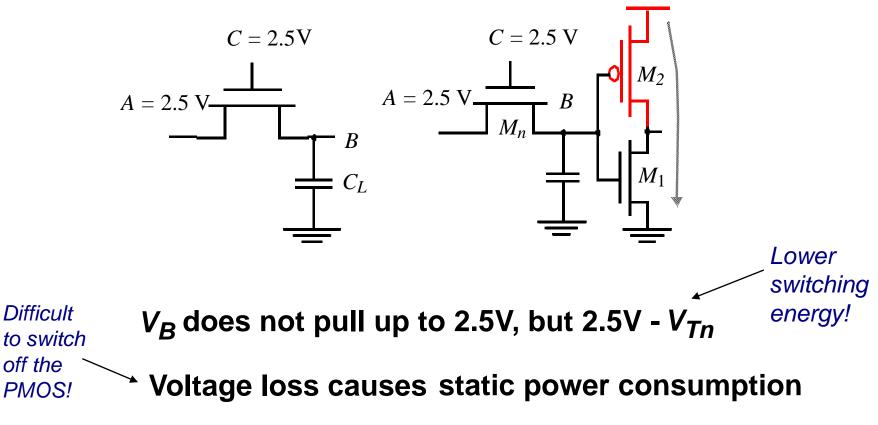


Let  $B=V_{DD}$ , A=1 (NMOS ( $M_1$ ) pulling up node X):  $V_x = V_{DD}-V_{tn1}$ Let C=1 (NMOS ( $M_2$ ) pulling up node Y):  $V_Y=(V_{DD}-V_{tn1})-V_{tn2}$  Let  $B=C=V_{DD}$ , A=1  $V_X = V_{DD}-V_{tn1}$  &  $V_Y = V_{DD}-V_{tn2}=V_{DD}-V_{tn1}$ (assuming  $Vt_{n1}=Vt_{n2}$ )

Note: Vgs>Vtn for NMOS to turn ON.

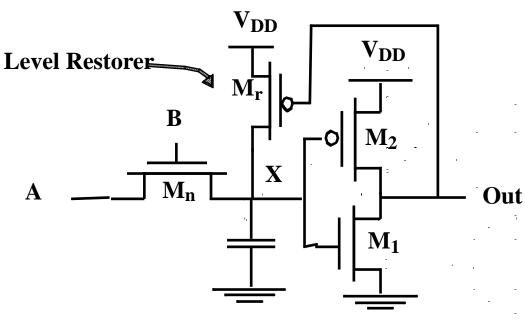
### NMOS-only Switch

off the



NMOS has higher threshold than PMOS (body effect)

#### Solutions to the Voltage Drop Problem: Solution 1: Level Restoring Transistor



Pass Transistor Logic suffers from static power dissipation and reduced NMs

At  $B=V_{DD}$ , if A: 0 to  $V_{DD}$   $V_x = V_{DD}-V_{Tn}$ , Out=0,  $M_r=ON$  and  $V_x=V_{DD}$ 

Eliminates static power in the Inverter

No static power between *M<sub>r</sub>* and *M<sub>n</sub>* 

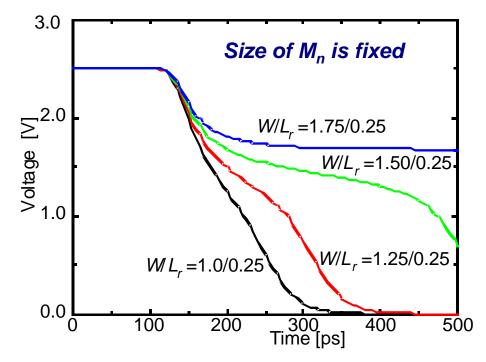
#### Advantage: Full Swing

• Restorer adds capacitance, takes away pull down current at X (for high to low transition at X,  $M_n$  must be stronger than  $M_r$ ), can slow down gate

#### Ratio problem

#### **Restorer Sizing**

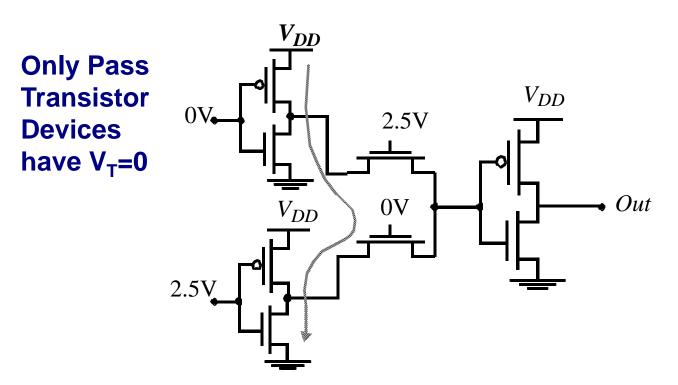
Need to size  $M_n$  and  $M_r$  to bring  $V_x < V_M (=V_{DD}/2)$  ( $V_M$  is a function of R1 and R2) R1 and R2 are the equivalent on-resistances of M1 and M2



- Upper limit on restorer size when too large (R<sub>r</sub> too small), V<sub>x</sub> can't be brought below V<sub>M</sub>
- Pass-transistor pull-down can have several transistors in stack

Transient Response: V<sub>x</sub> vs. time

# Solution 2: Single Transistor Pass Gate with $V_T=0$

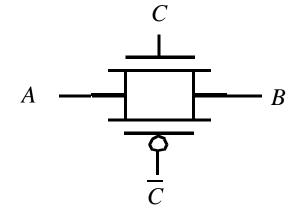


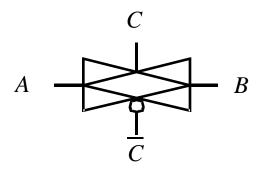
But even if V<sub>T</sub>=0, there is still body effect...which prevents full swing!

WATCH OUT FOR LEAKAGE CURRENTS in the IDLE State!!!

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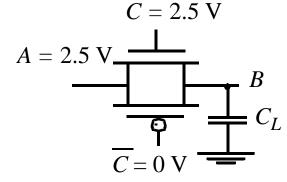
#### **Solution 3: Transmission Gate**





Acts like a bidirectional switch controlled by the gate signal C

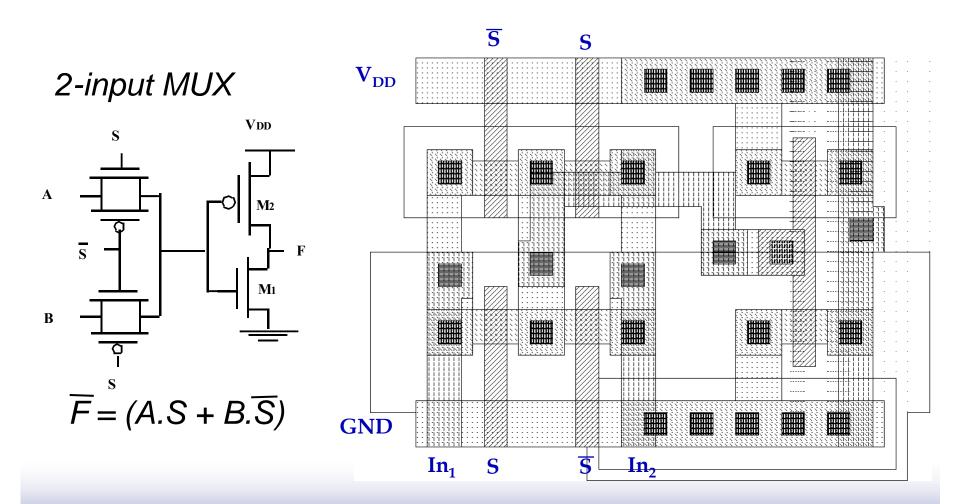
When C=1, both MOSFETS are ON allowing the signal to pass through the gate (A=B, if C=1)



Because of the PMOS, C<sub>L</sub> charges to Vdd

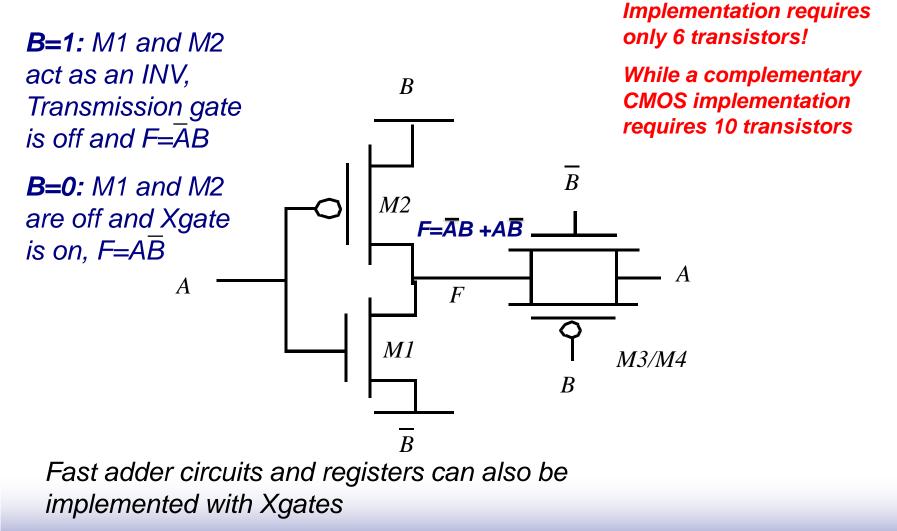
Because of NMOS C<sub>L</sub> discharges to 0

#### **Pass-Transistor Based Multiplexer**

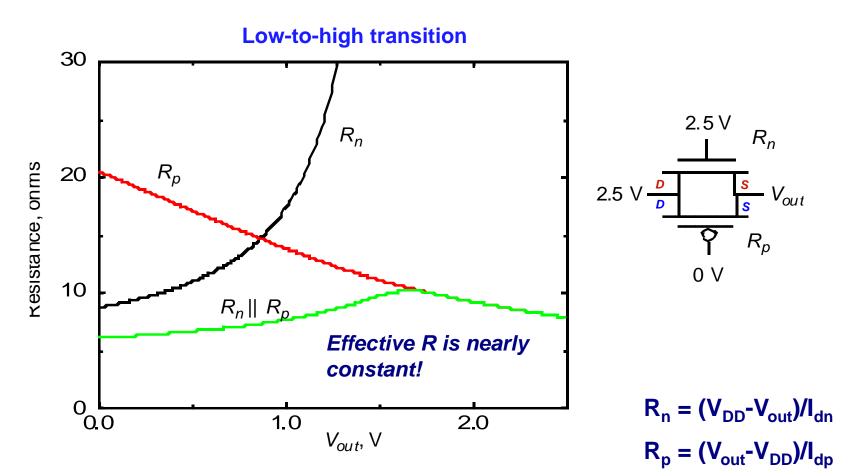


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#### **Transmission Gate XOR**



#### **Resistance of Transmission Gate**



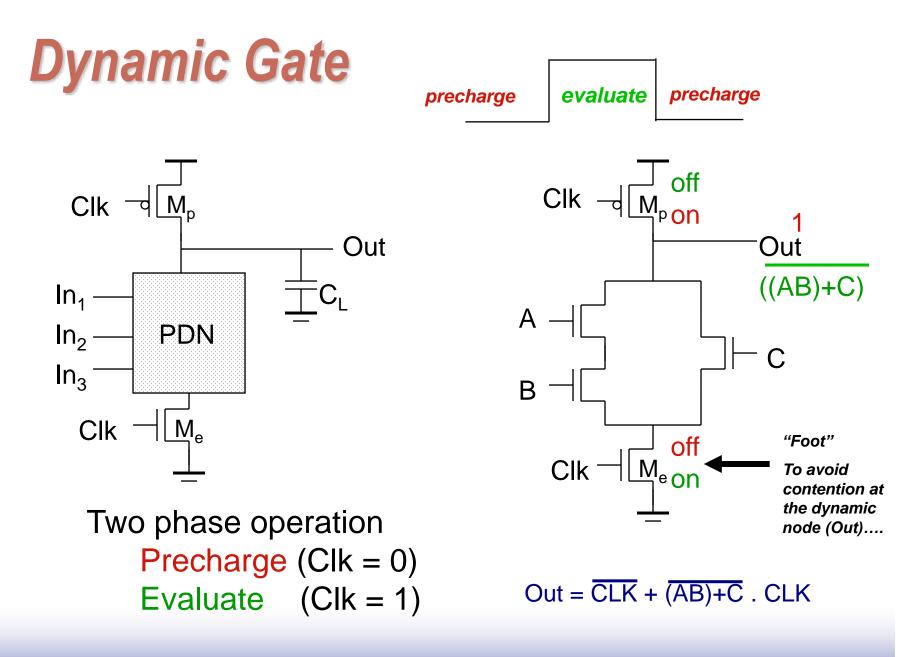
When Vout is low, NMOS is working, hence Rn dominates the equivalent resistance....similarly Rp dominates when Vout is high.....

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#### **Dynamic CMOS**

- □ In static circuits at every point in time (except when switching) the output is connected to either GND or V<sub>DD</sub> via a low resistance path.
  - fan-in of *n* requires 2n (*n* N-type + *n* P-type) devices (for static CMOS)
- Dynamic circuits rely on the temporary storage of signal values on the capacitance of high impedance nodes.
  - requires only n + 2 (n+1 N-type and 1 P-type) transistors



#### **Conditions on Output**

- During evaluation phase, the only possible path between output node and supply rail is to ground. Hence, once the output of a dynamic gate is discharged, it cannot be charged again until the next precharge operation.
- Inputs to the gate can make at most one transition during evaluation.
- Output can be in the high-impedance state during and after evaluation (if PDN is off), state is stored on C<sub>L</sub>

#### **Properties of Dynamic Gates**

- □ Logic function is implemented by the PDN only
  - number of transistors is N + 2 (versus 2N for static complementary CMOS)
- □ Full swing outputs ( $V_{OL} = GND$  and  $V_{OH} = V_{DD}$ )
- Non-ratioed sizing of the devices does not affect the logic levels
- □ PDN starts to work as soon as the input signals exceed  $V_{Tn}$ , so  $V_{M}$ ,  $V_{IH}$  and  $V_{IL}$  equal to  $V_{Tn}$   $V_{OH}$   $NM_{H}$
- $\Box$  Low noise margin (NM<sub>L</sub>)
- □ Needs a precharge/evaluate clock
- □ Faster switching speeds:
  - reduced load capacitance due to lower input capacitance (C<sub>in</sub>) resulting from lower number of transistors per gate and single transistor load per fan-in (reduced logical effort, 2/3 for a 2-input dynamic NOR)
  - no I<sub>sc</sub>, so all the current provided by PDN goes into discharging C<sub>L</sub>

 $V_{OL} - NM_{L} - V_{IL}$ "0" • N<sub>ML</sub> = V<sub>IL</sub> - V<sub>OI</sub>

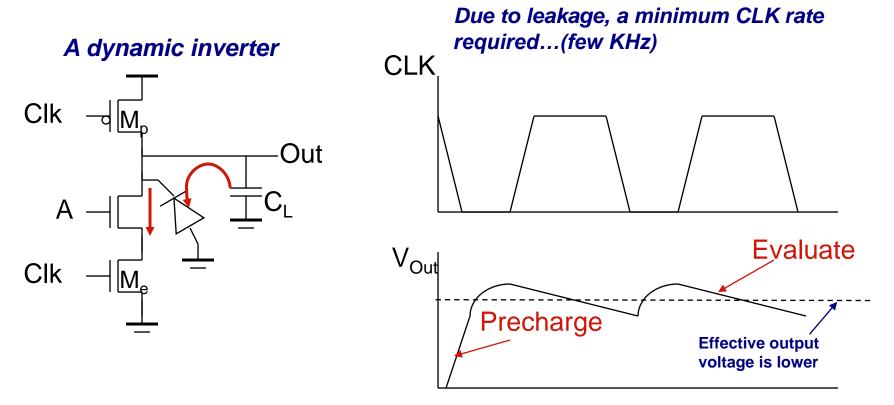
•  $N_{MH} = V_{OH} - V_{HH}$ 

### **Properties of Dynamic Gates**

□ Advantages:

- Lower physical capacitance: uses fewer transistors
- No glitching (dynamic gates can have at most one transition per CLK cycle)
- Only consumes dynamic power....no static current path ever exists between V<sub>DD</sub> and GND (including P<sub>sc</sub>)
- In spite of the above....overall power dissipation usually higher than static CMOS
  - CLK power can be significant: extra load on Clk + transition every CLK cycle
  - Number of transistors is more than the minimal set required for implementing logic
  - Higher switching activity due to higher transition probabilities

# Issues in Dynamic Design 1: Charge Leakage



Leakage sources: reverse biased diode and subthreshold

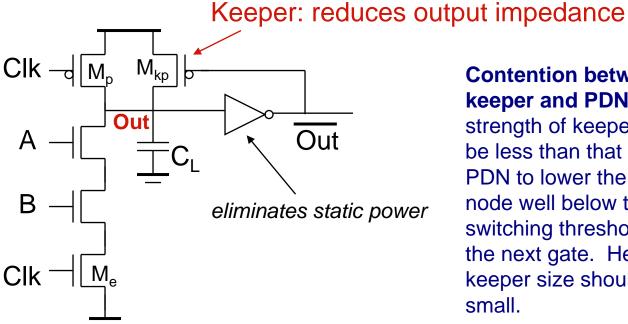
#### Dominant component is subthreshold current

Note: leakage of precharge PMOS can partially compensate for the charge loss at the dynamic node

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#### Solution to Charge Leakage

Same approach as level restorer for pass-transistor logic

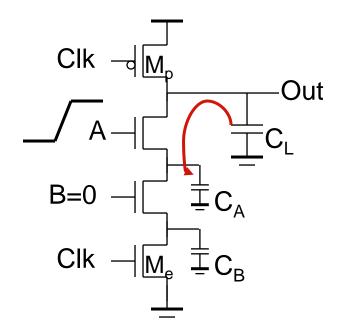


**Contention between** keeper and PDN---

strength of keeper must be less than that of the PDN to lower the out node well below the switching threshold of the next gate. Hence keeper size should be small.

H. F. Dadgour and K. Banerjee, "A Novel Variation-Tolerant Keeper Architecture for High-Performance Low-Power Wide Fan-in Dynamic Gates," IEEE Transactions on VLSI Systems, Vol. 18, No. 11, pp. 1567-1577, 2010.

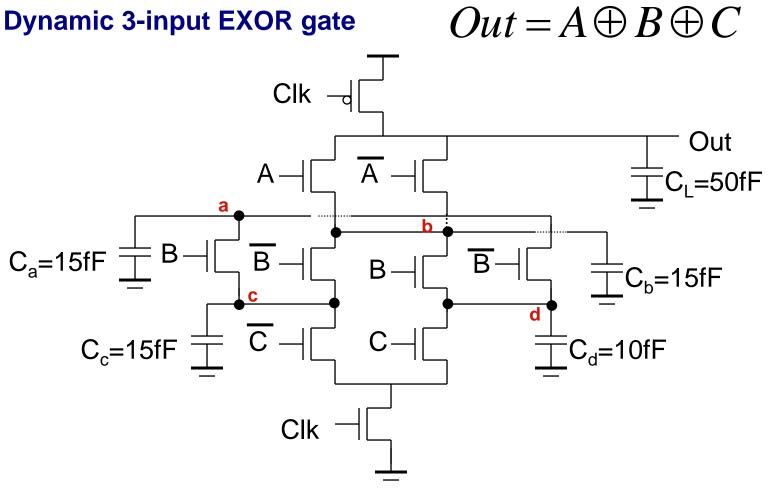
### **Issues in Dynamic Design 2: Charge Sharing**



Charge stored originally on  $C_L$  is redistributed (shared) over  $C_L$  and  $C_A$  leading to reduced robustness

Output node voltage drops and cannot be recovered due to the dynamic nature of the circuit.

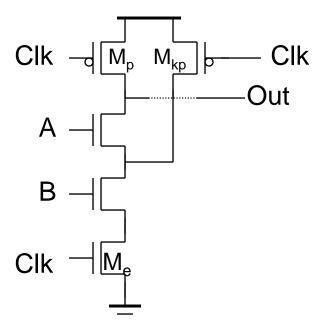
#### **Charge Sharing Example**



Worst case change in Output is obtained by exposing the maximum number of internal capacitances to the output: this happens for ABC or ABC

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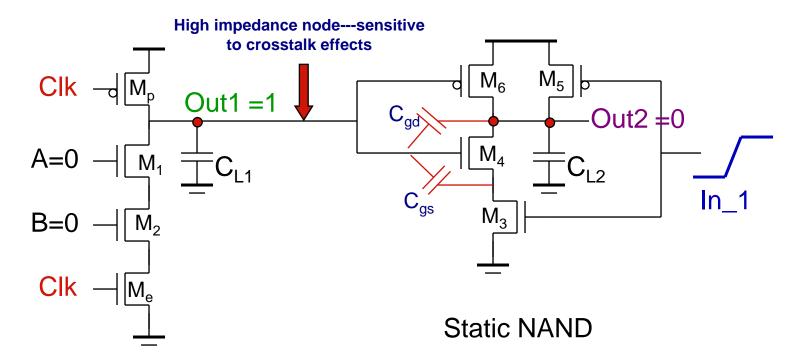
#### **Solution to Charge Redistribution**



Precharge internal nodes (to  $V_{DD}$ ) using a clock-driven transistor (at the cost of increased area and power)

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# Issues in Dynamic Design 3: Backgate (Output-to-input) Coupling



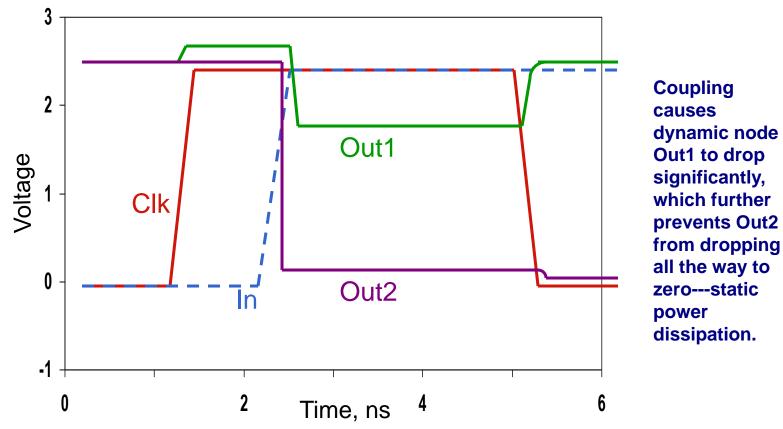
Dynamic NAND

Capacitive coupling between dynamic node Out1 and H-L transition at Out2 (when In\_1 goes high) through the gate-drain and gate-source capacitance of M4

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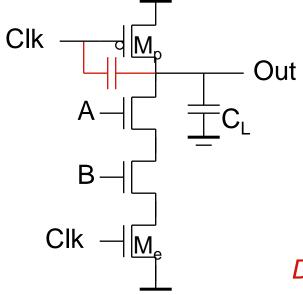
#### **Backgate Coupling Effect**

Simulation result



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# Issues in Dynamic Design 4: Clock Feedthrough



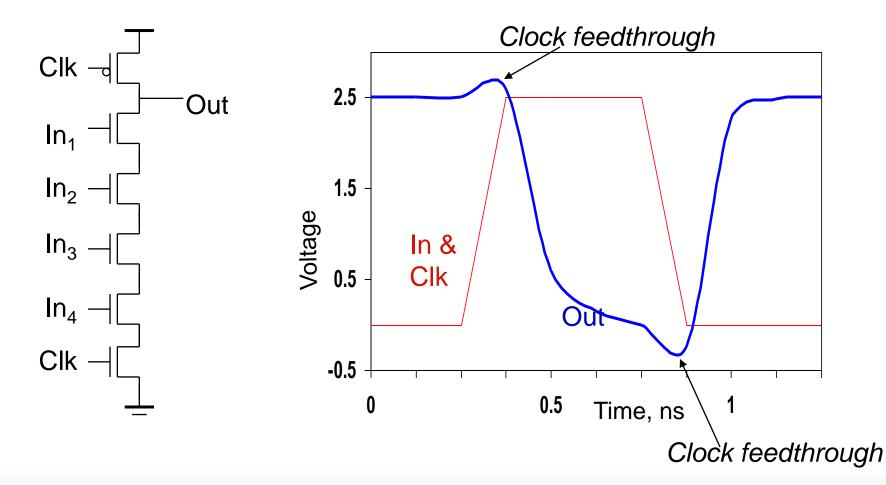
Coupling between Out and Clk input of the precharge device due to gate to drain capacitance (includes both overlap and channel).

Hence, voltage of Out can rise above  $V_{DD}$  on the L-H Clk transition (assuming PDN is off). The fast rising (and falling edges) of the clock couple to Out.

Dynamic circuits need careful simulation!

Clk feedthrough can cause normally reverse biased junction diodes of the precharge transistor to become forward biased---causing electron injection into the substrate that can be collected by a nearby highimpedance node in the 1 state, eventually resulting in faulty operation.

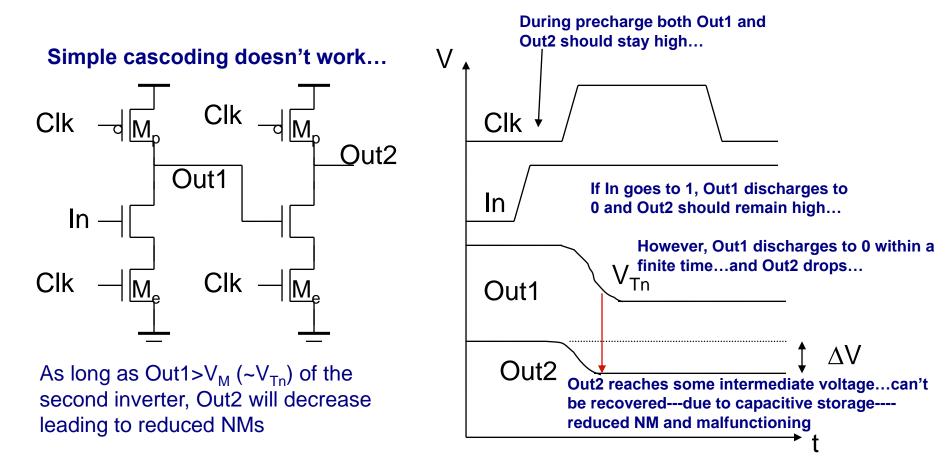
#### **Clock Feedthrough**



#### **Other Effects**

Capacitive coupling
Substrate coupling
Minority charge injection
Supply noise (ground bounce)

#### **Cascading Dynamic Gates**

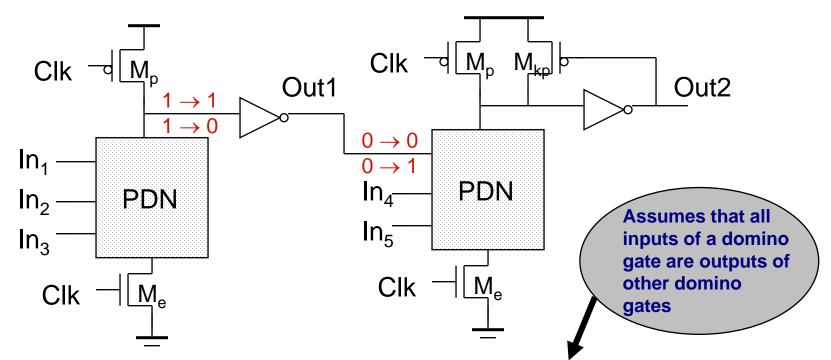


**Solution:** Set all inputs to 0 during precharge For correct operation only  $0 \rightarrow 1$  transitions should be allowed at inputs!

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#### **Domino Logic**

An n-type dynamic logic followed by a static inverter...

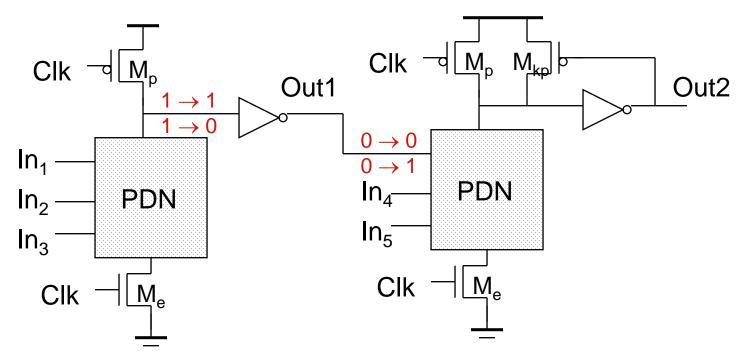


All inputs (are outputs of other Domino gates) are set to 0 at the end of precharge phase

Only 0 to 1 transition at the inputs during evaluation phase: during evaluation, dynamic gate conditionally discharges and the output of the inverter makes a conditional transition from 0 to 1.

#### **Domino Logic**

An n-type dynamic logic followed by a static inverter...



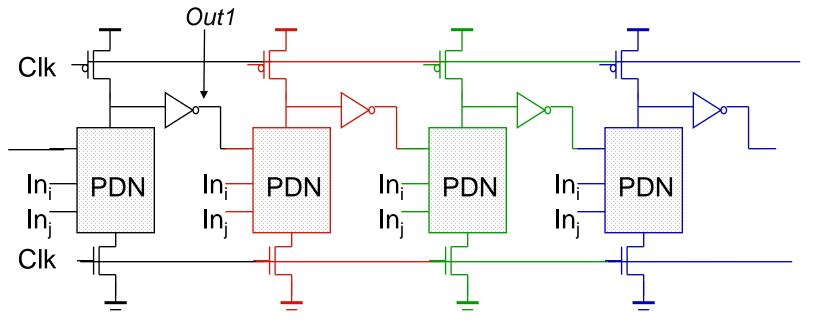
The static inverter reduces the capacitance of the dynamic output node by separating internal and load capacitances.....it also increases the NM (due to the low-impedance output)

The inverter can also be used to drive a keeper device to combat leakage and charge redistribution.

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### Why Domino?

#### A Domino chain



Precharge: all inputs=0

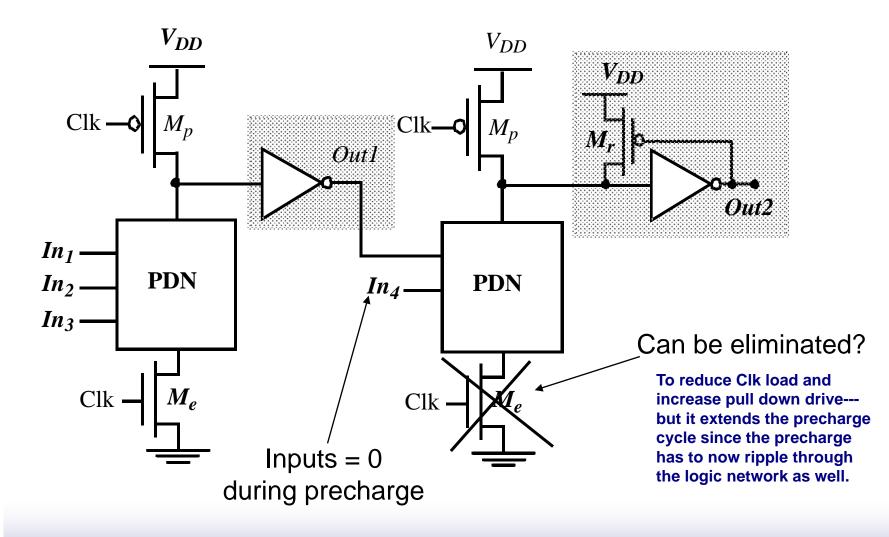
**Evaluation**: Output of domino1 either stays at 0 or makes a transition from 0 to 1, affecting the second gate. This effect might ripple through the whole chain...*like a line of falling dominos!* 

# **Properties of Domino CMOS Logic**

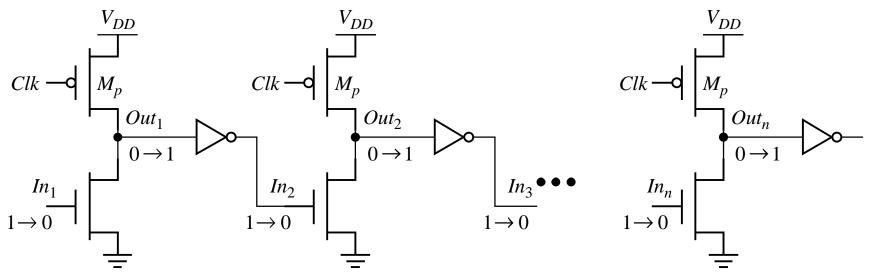
 Only non-inverting logic can be implemented (due to the static inverter)

- Major limitation
- Can be overcome using dual-rail domino (an expensive solution)
- Very high speed
  - Only rising edge delays, and t<sub>pHL</sub>=0
  - static inverter can be skewed to match the fanout, which is already much smaller than in the complimentary case, since only a single gate capacitance needs to be accounted for per fan-out gate.
  - Input capacitance reduced smaller logical effort

#### **Designing with Domino Logic**



#### **Footless Domino**



If  $In_1=1$ ,  $out_1=0$  and  $In_2=1$ 

On the falling edge of CLK, let  $In_1 = 0$ : but it takes two gate delays for  $In_2$  to be 0, during which second gate cannot pre-charge its output (Out<sub>2</sub>), since PDN is fighting the precharge-PMOS

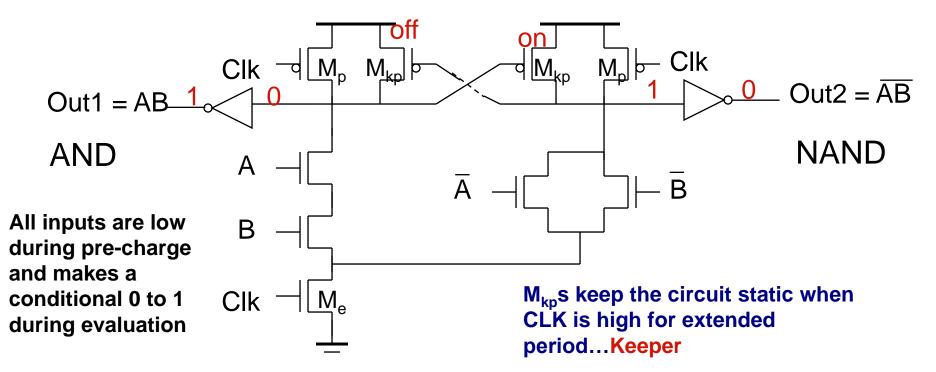
Time taken to precharge equals the critical path delay! Better to use the evaluation device....

Pre-charge is rippling – short-circuit current A solution is to delay the clock for each stage

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#### **Differential (Dual Rail) Domino**

Overcomes the non-inverting property of Domino Logic: used commercially in several microprocessors Uses a pre-charged load....



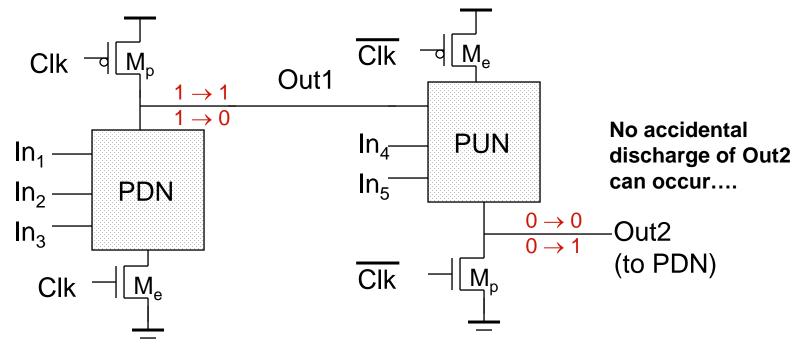
Possible to implement any arbitrary function....but comes at the expense of increased power since a transition is guaranteed every CLK cycle irrespective of the input values....either Out1 or Out2 must make a 0 to 1 transition.



Alternative to cascading dynamic gates....uses n-type and p-type dynamic logic

Exploits duality between n-tree and p-tree logic gates to eliminate cascading problem

No extra inverter at the outputs....unless output of n-tree (p-tree) needs to be connected to another ntree (p-tree) gates



Only  $0 \rightarrow 1$  transitions allowed at inputs of PDN Only  $1 \rightarrow 0$  transitions allowed at inputs of PUN

Drawback: p-tree gates are slower than the n-tree gates...needs proper skewing of PMOS....area penalty No buffers---so dynamic nodes need to be routed between gates

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