

## Background

Nearly 20% of the world's population lives in or near elephant habitats. Crop-raiding is the main conflict between elephants and humans. In small plantations, 200-600 pounds of food is lost per day, and a few thousand dollars is lost per household per raid. In large plantations, which produce mainly palm oil and timber, 105 million dollars is lost each year. In India 100-300 humans and 40-50 elephants are killed during cropraiding each year. Around the globe, 500 people are killed by elephant each year according to National Geographic Channel documentary *Elephant Rage*.

# Task Flow Chart



# **Block Diagram**





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## Solving Elephant-Human Conflict with UAVs Weiyun Jiang | Alexis Yang | Ning Du Jiajun Wan

# **Drone System Setup**





# Key Components

#### IMX219-120 Camera

Sony 8-megapixel sensor, 120-degree field of view for elephant detection and tracking. Dimension 25x24mm

#### **NVIDIA Jetson Nano**

ARM Cortex-A57 and Maxwell GPU. Onboard processor for computer vision tasks. PCB dimension: 70x45mm

### **DJI N3 Flight Controller**

Dual IMU Redundancy, GNSS Compass, and PMU for flight stability. Controller: 57.9x39x17mm PMU: 40x 28.2x11.2mm GPS-Compass: 50 (diameter)x12.2mm

Collect GPS coordinates on the tag. Update rate 1 - 10 Hz. Position Accuracy < 3 meters. Dimension: 16x16x5.2mm

#### **FGPMMOPA6H GPS**



- Expected battery life: 198 days





- elephant away



# UC SANTA BARBARA **College of Engineering**

 Neural network-based elephant detection • Optical flow for real-time elephant tracking • Localization data fed into a control algorithm to herd the

# **Simulation Result**

• Xbee module used to send out GPS coordinates • SD card provides storage for location logging • Dimension: 8.4x8.4mm Weight: 26.3g

ATmega328P

Xbee