AFRMUDA

Fall 2019 Final Design Review



Development Team

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- IMU, KerberosSDR Interface

- KerberosSDR Interface, Triangulation

- Emitters, Triangulation

- Emitters, IMU



Project Description

- <u>Goal</u>: To plan against potential GPS loss, such as jamming or in locations without GPS, by acting as an alternative location tracking system
- GPS uses satellites; Bermuda is a proof of concept that location can be found using radio emitters.



System Architecture

- KerberosSDR
- Microcontroller (Raspberry Pi 3 B+)
- Adafruit Breakout Board
- RadioFruit Emitters
- AeroVironment drone



Block Diagram





IMU (Inertial Measurement Unit)

- know Bermuda's absolute starting location
- + know acceleration or velocity
- + know direction
- = can estimate location

Not very accurate due to:

- wind
- drift (error accumulation)



Requires:

- Radio emitters
- Radio emitters' absolute location and frequency range
- Bermuda's estimated location from IMU



1. Determine nearest emitters. Plot them.





2. Get direction to each emitter from the KerberosSDR.



Bermuda's Triangulation

3. Combine a point and a slope to get a line: $y - y_1 = m(x - x_1)$



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4. The intersection is the absolute location of the Bermuda.





Current Progress

Experimentation with Hardware









Testing and Understanding Existing Software



Future Goals

End of Fall 2019 Goals:KerberosSDR able to detect emitters

Winter 2019 Goals:Triangulation and location finished



Applications

- Defense
- Warehouse Navigation
- Space Exploration
- Surgery



THANK YOU!!

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